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(71) Applicant(s)

Matsushita Electric Industrial Co., Ltd  
(Incorporated in Japan)  
1006, Oaza Kadoma, Kadoma-shi, Osaka 571, Japan

(72) Inventor(s)

Yuji Ariyoshi  
Toru Tanaka  
Masaneo Wakikawa  
Kiyoshi Ishioka

(74) Agent and/or Address for Service

Gill Jennings & Every  
Broadgate House, 7 Eldon Street, LONDON,  
EC2M 7LH, United Kingdom

(51) INT CL<sup>7</sup>

G11B 17/028

(52) UK CL (Edition R )

G5R R8265 RPC6

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(58) Field of Search

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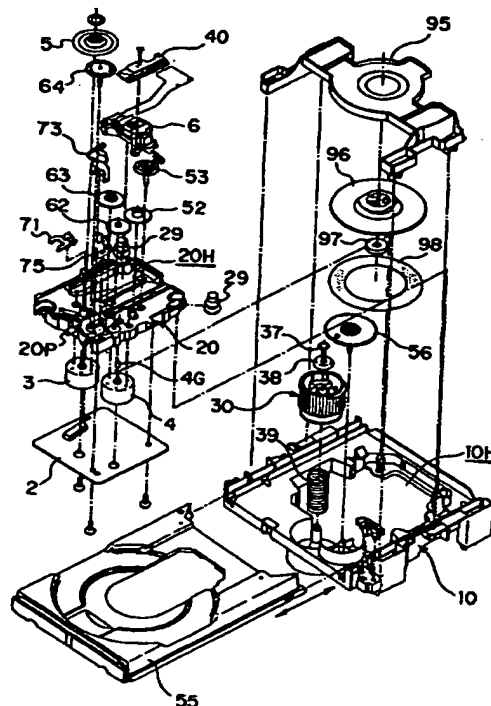
Online: EPODOC, WPI, PAJ

(54) Abstract Title

Optical disc drive having optical pickup and disc loading mechanism driven by the same motor

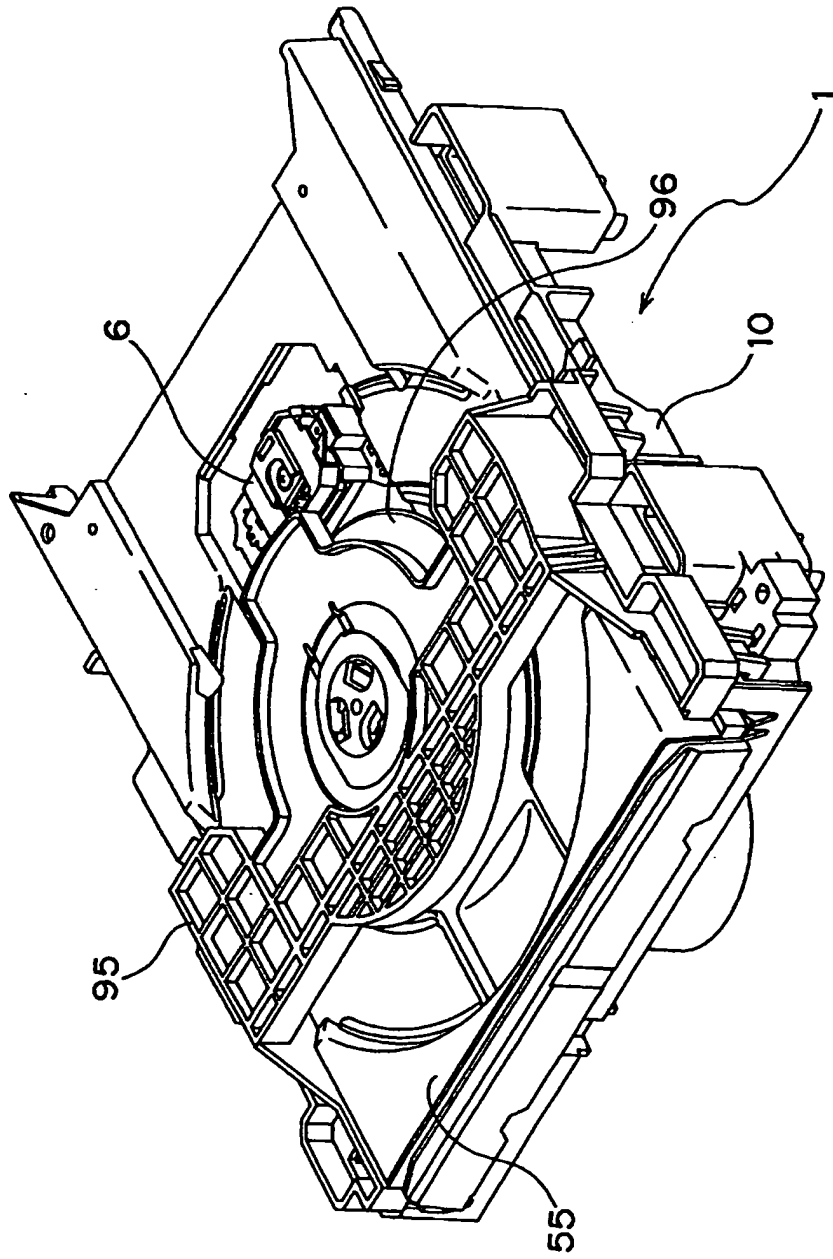
(57) A simplified optical disc drive in which the number of motors used for drive operation is reduced is described. The optical disc drive includes a first fixed drive base (10) and a second separate transverse base (20) which is vertically movable relative to the first base. A turntable (5), a first motor (3) for turntable drive, an optical pickup (6) and drive mechanism, and a disc loading drive mechanism are provided on base (20). A second motor (4) is provided on base (20) and can be driven in forward or reverse direction to supply drive power to the pickup drive mechanism and the disc loading drive mechanism by use of a drive power transfer path switching mechanism which switches the power transfer path from the pickup drive mechanism to the disc loading drive mechanism. By continuously driving the motor in one direction, the operations of moving the optical pickup, raising or lowering the turntable and transporting a disc can be sequentially performed, and by running the motor in the opposite direction, the sequence may be performed in reverse order. Also described are elastic damping means to mount the second base to the first base in order to reduce the effect of shock or vibrations received by the disc drive.

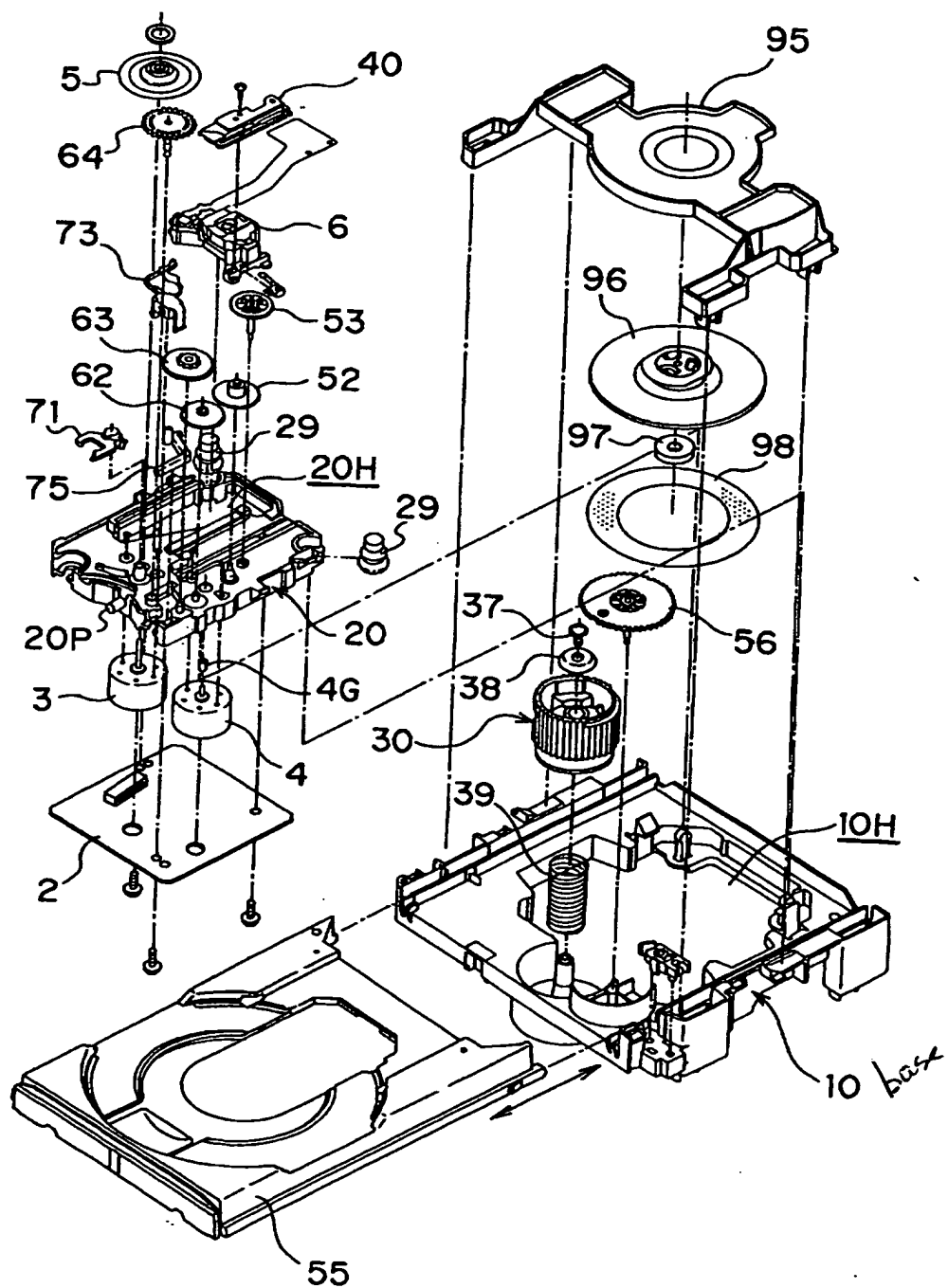
Fig. 2

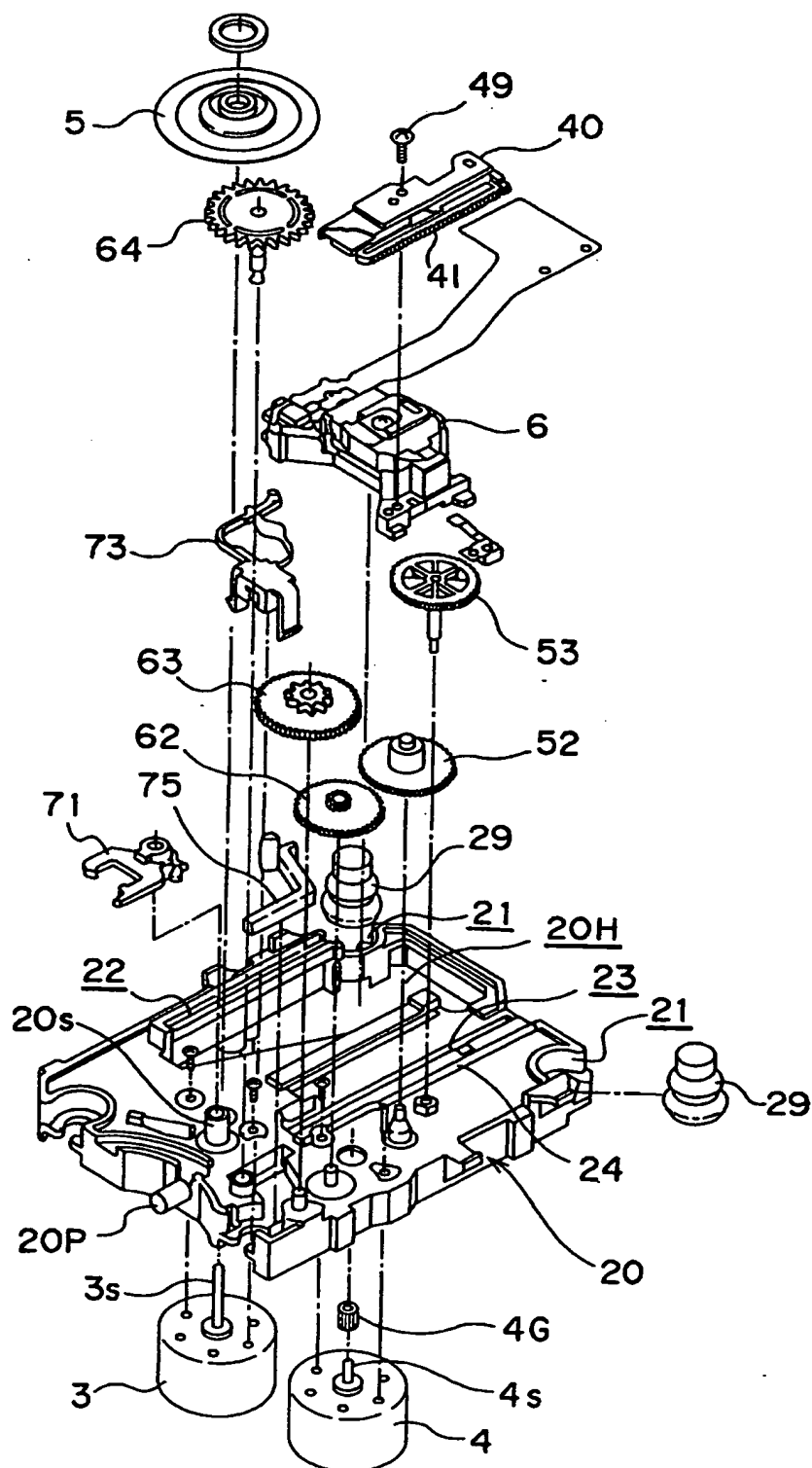


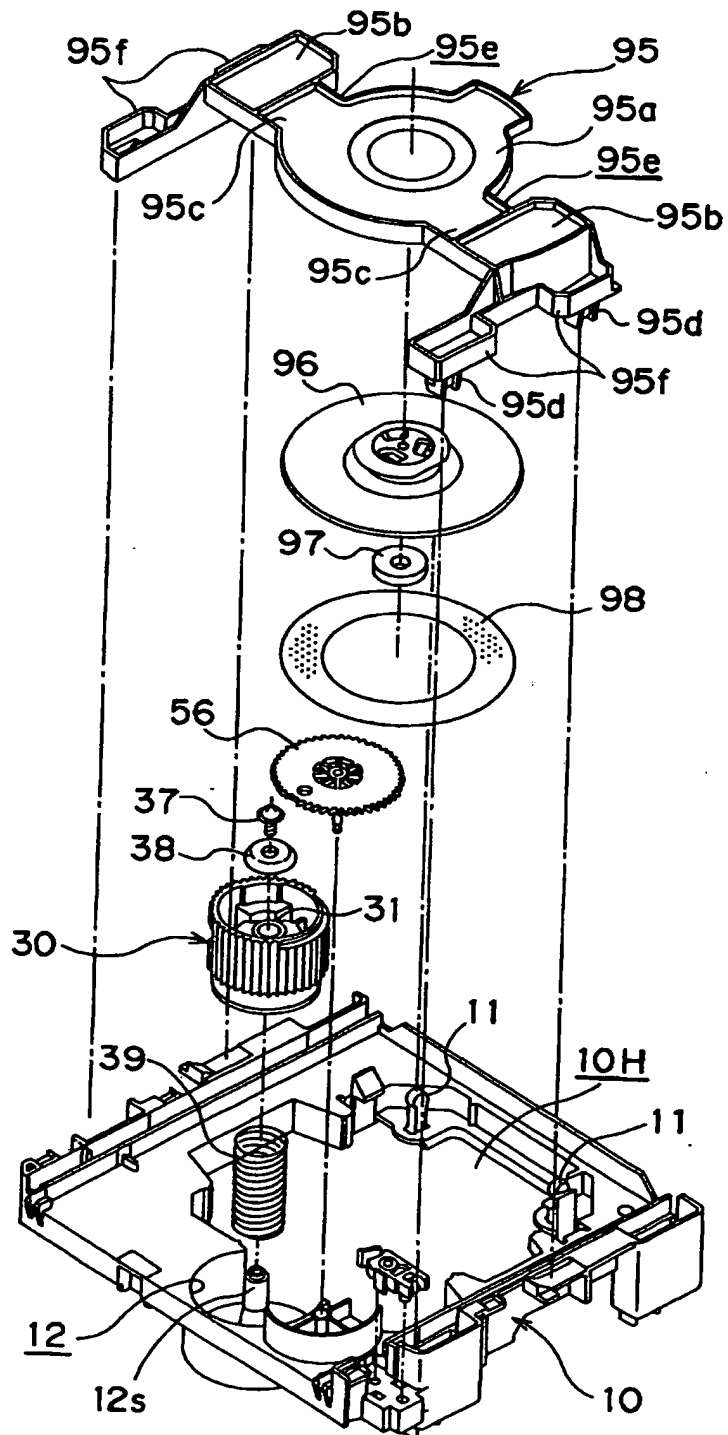
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Fig. 1



*Fig. 2*

*Fig. 3*

*Fig. 4*

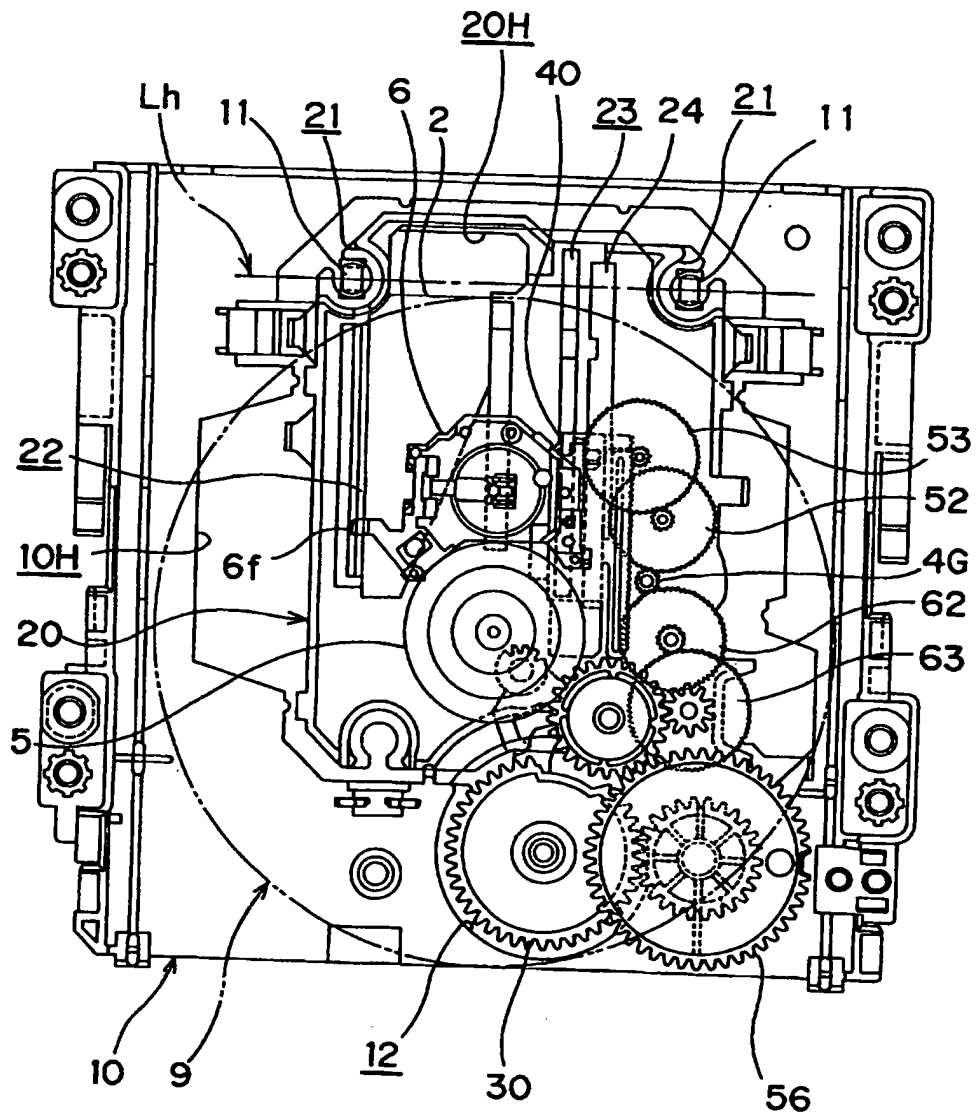
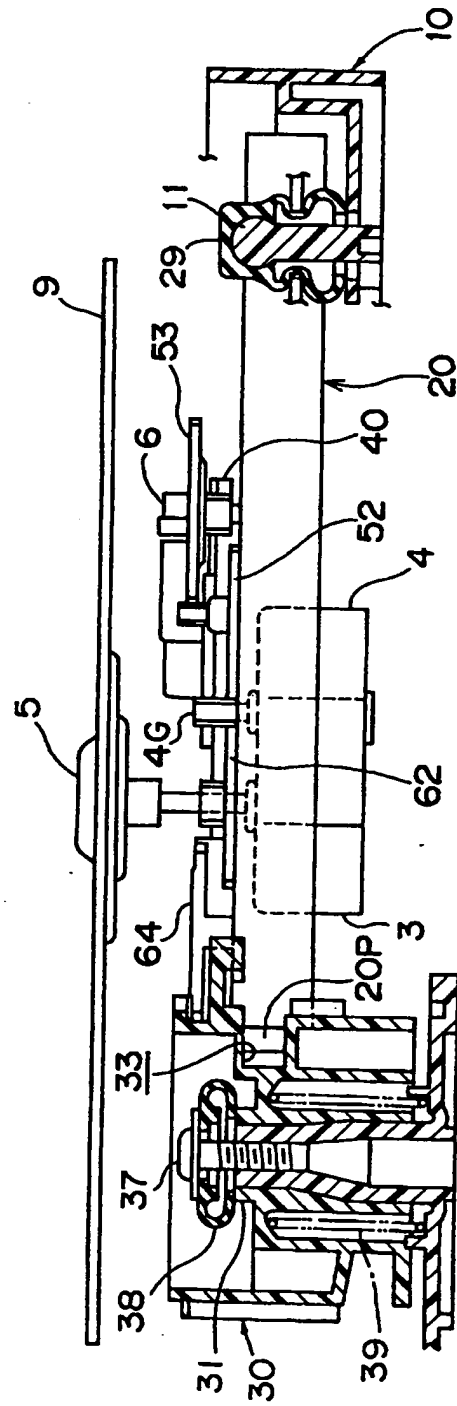
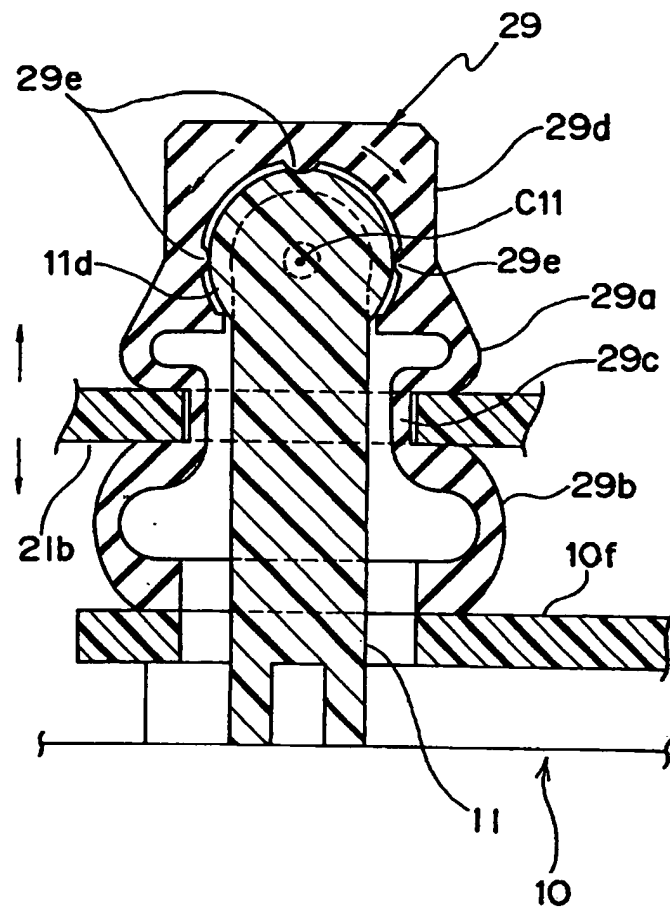
*Fig. 5*

Fig. 6

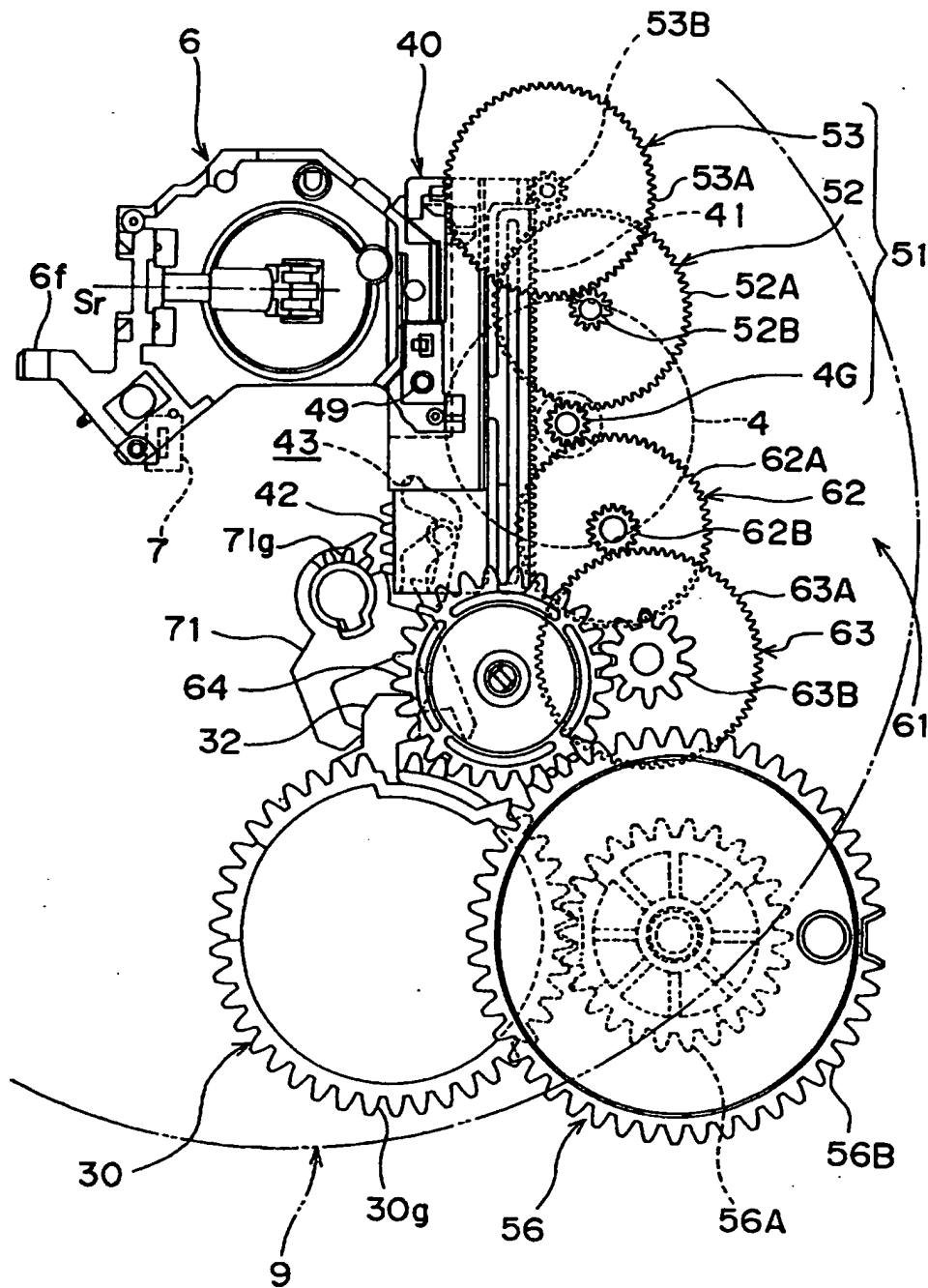


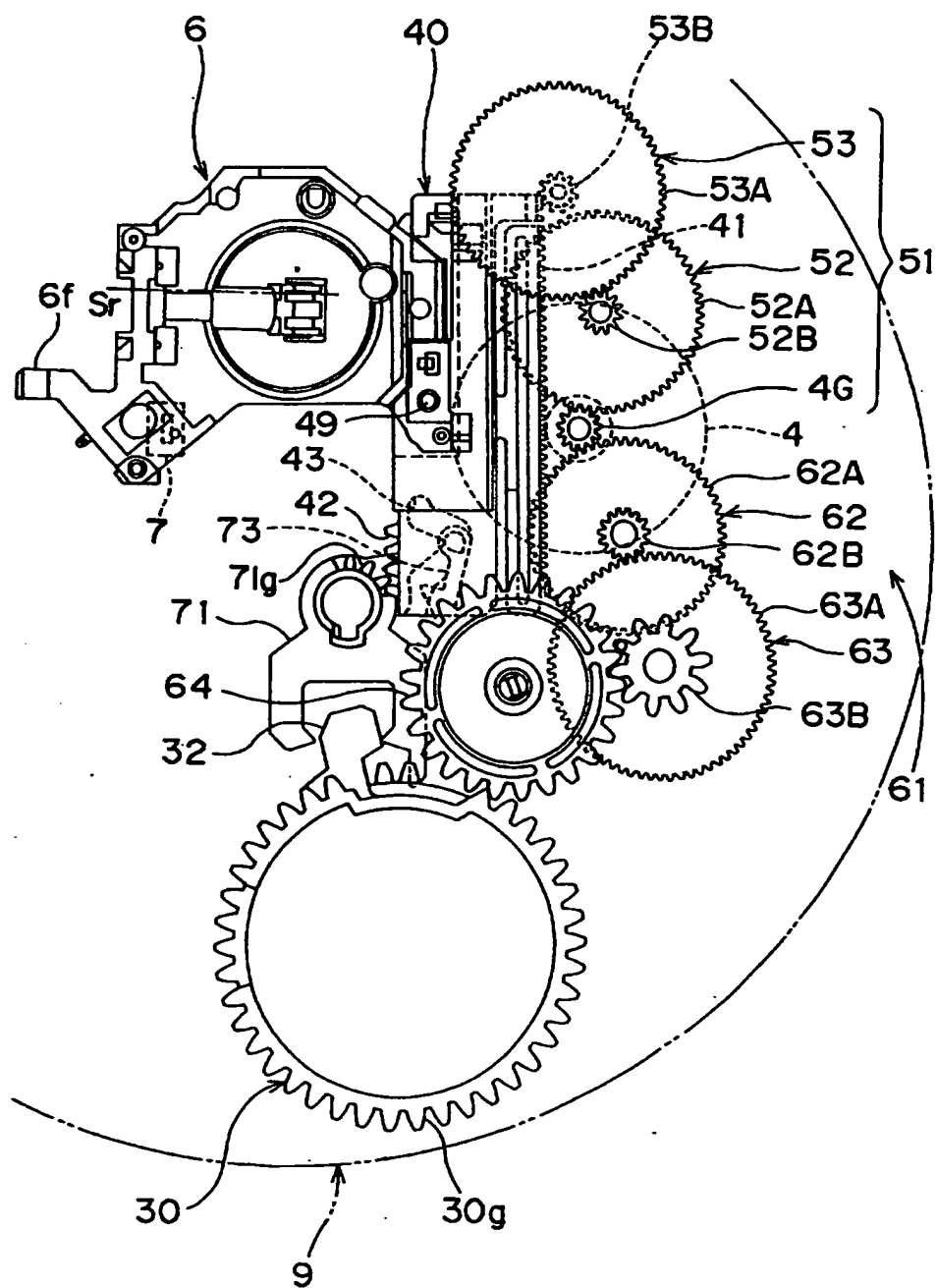


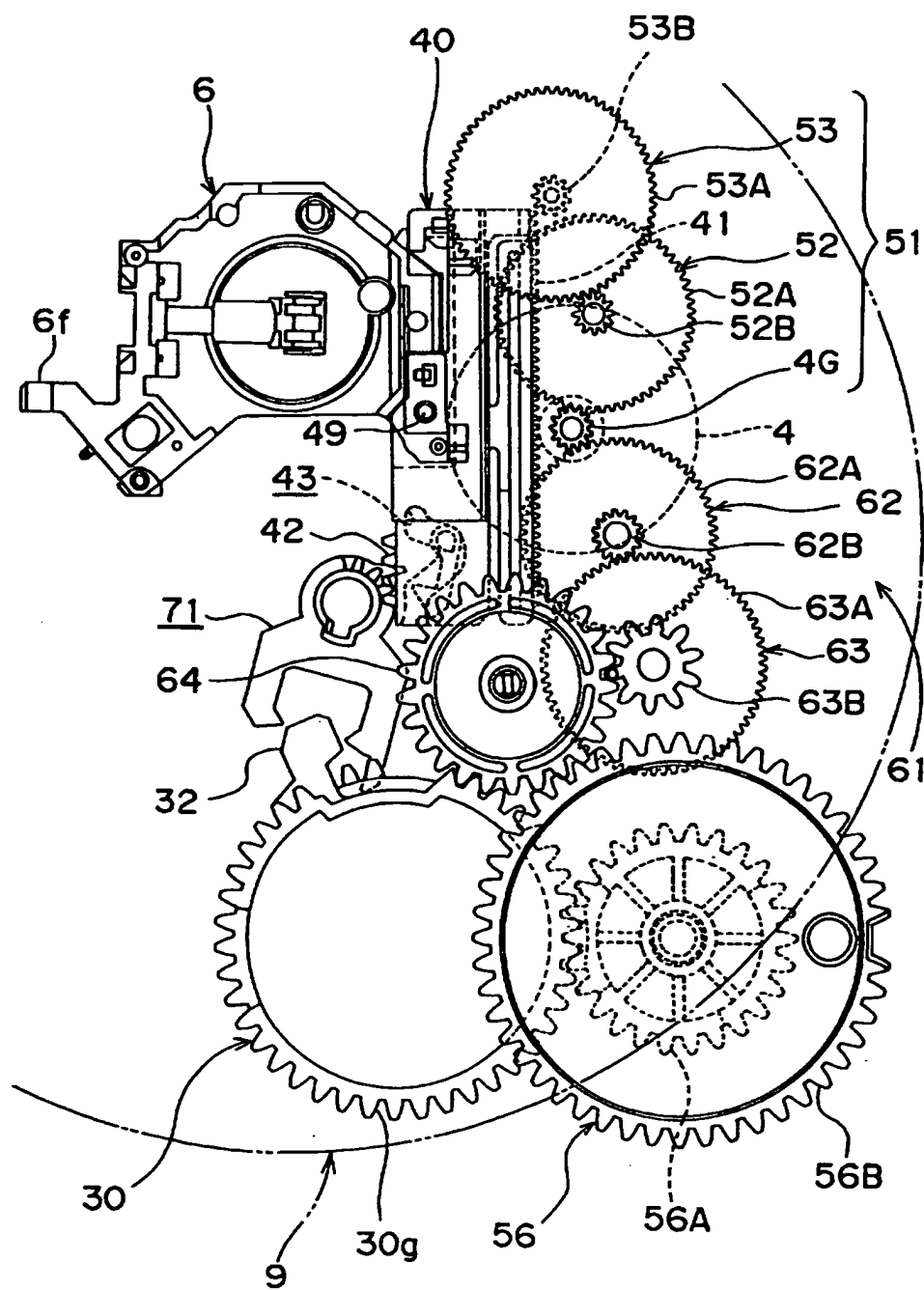


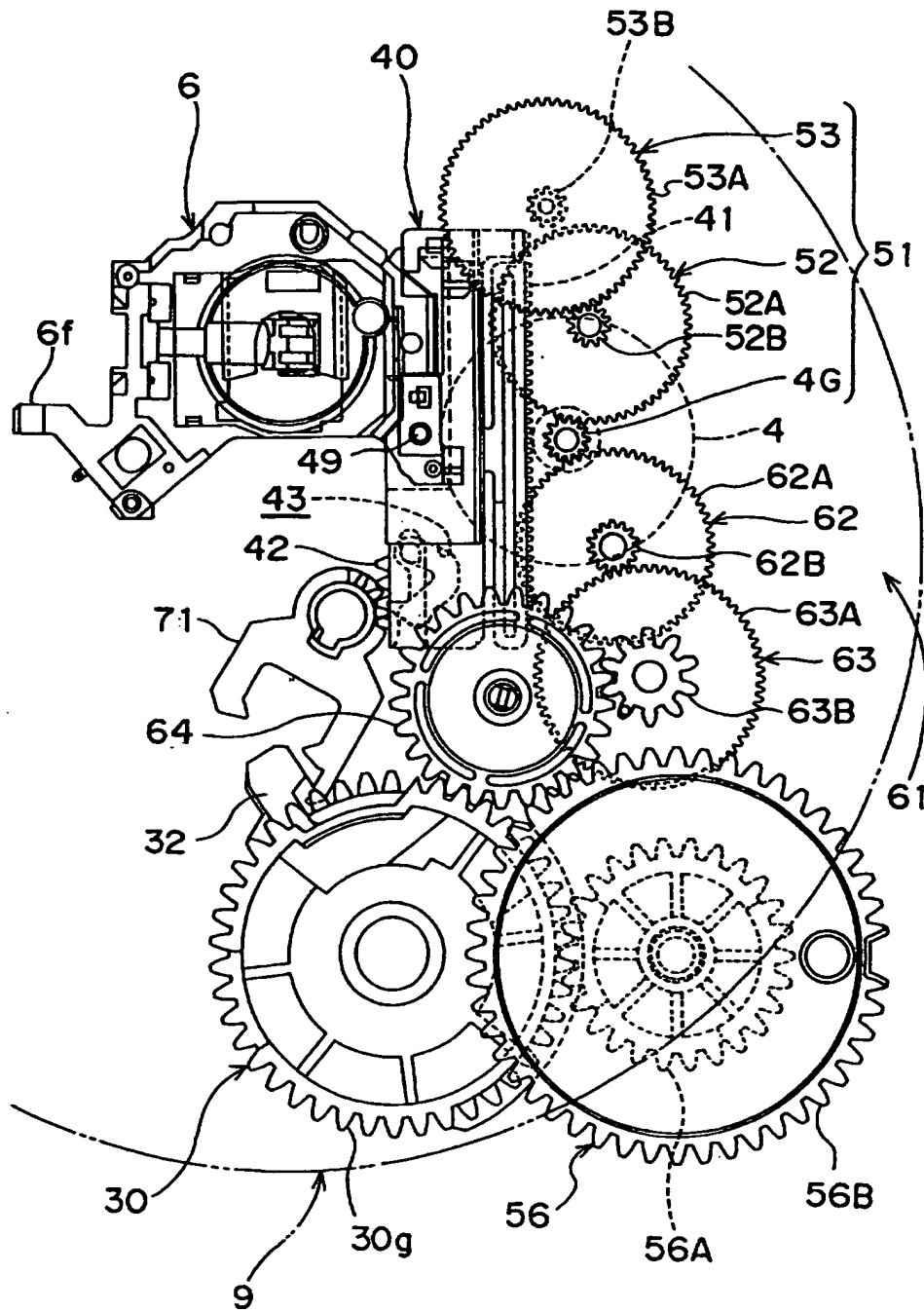
*Fig. 8*

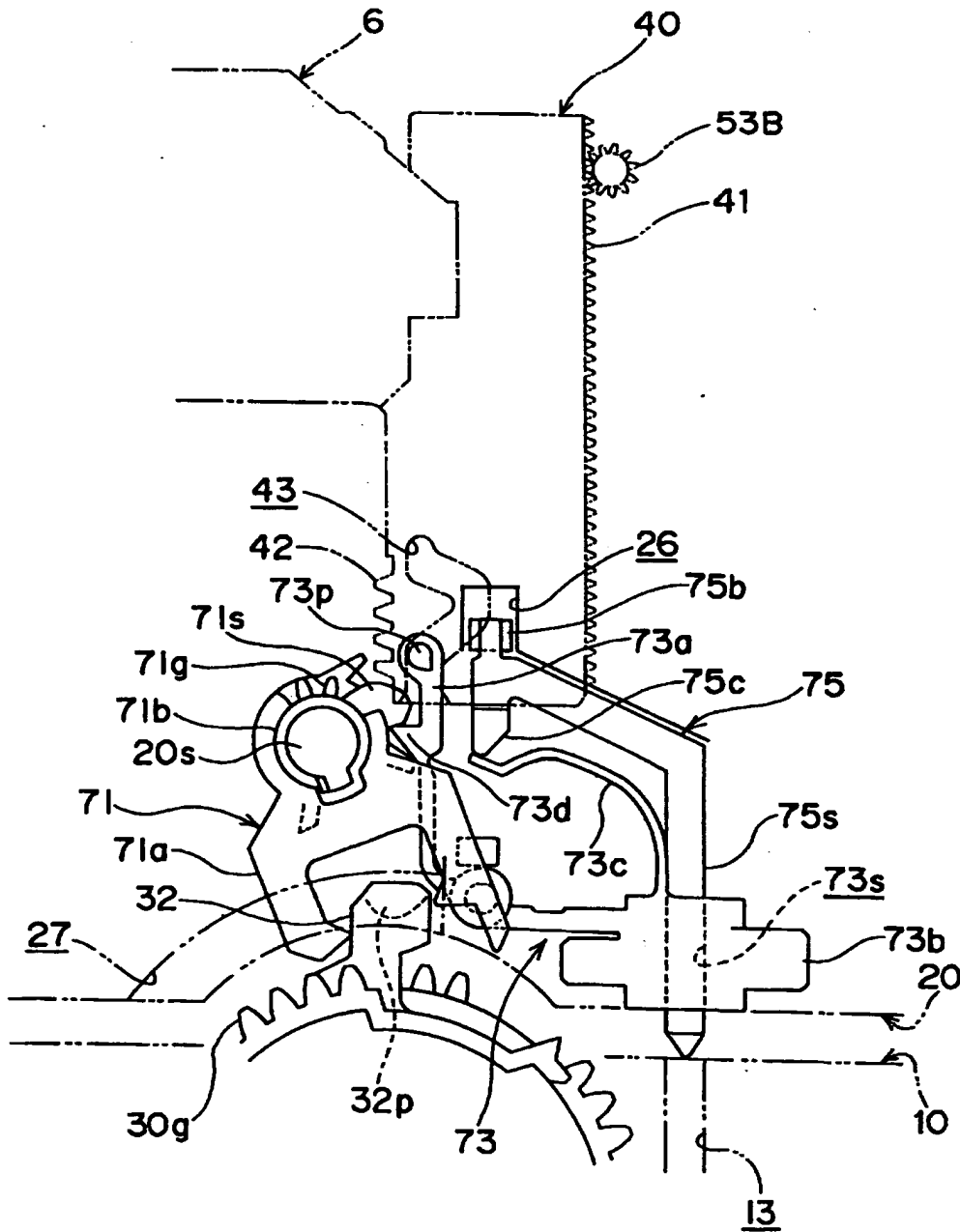


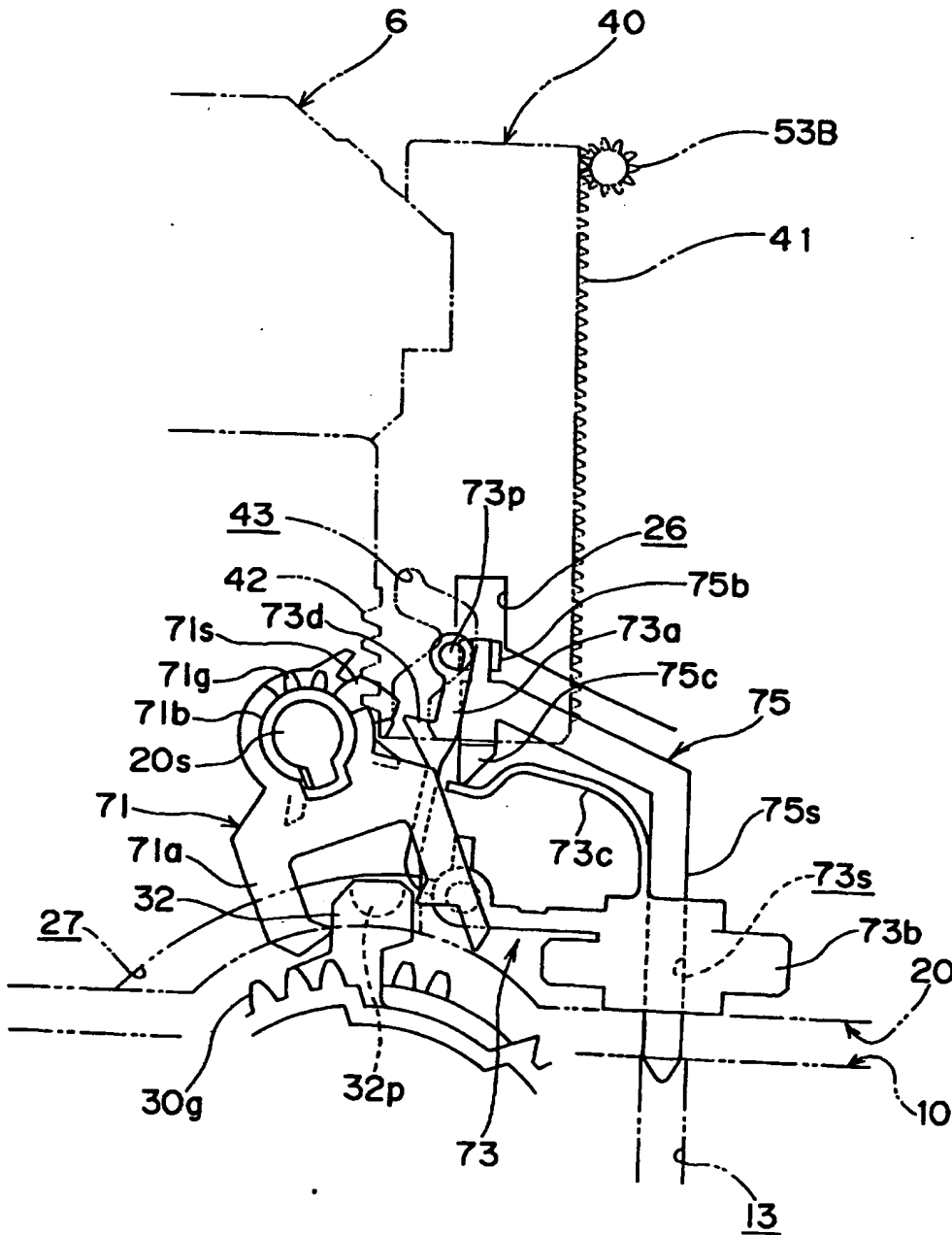
*Fig. 10*

*Fig. 11*

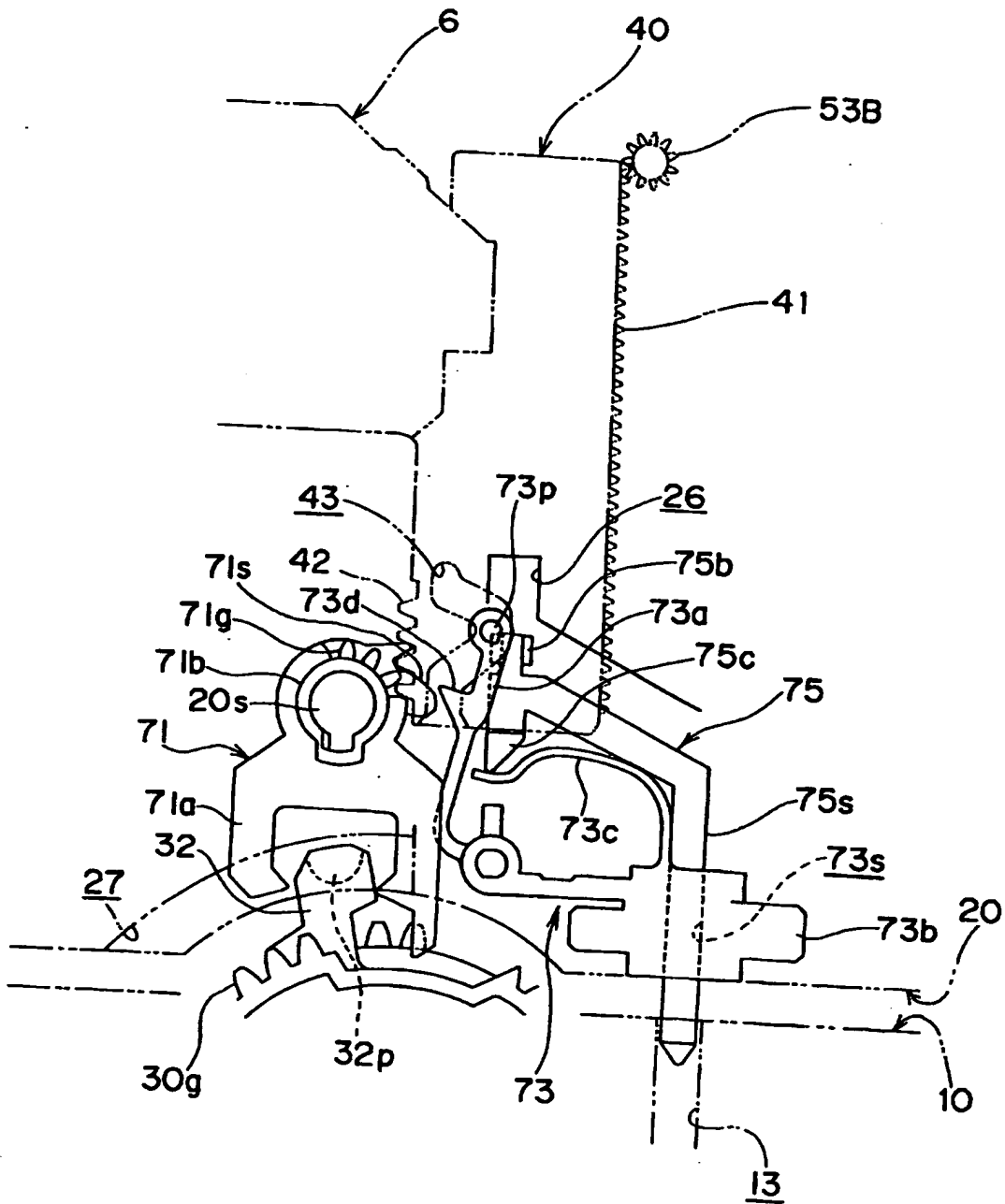
*Fig. 12*

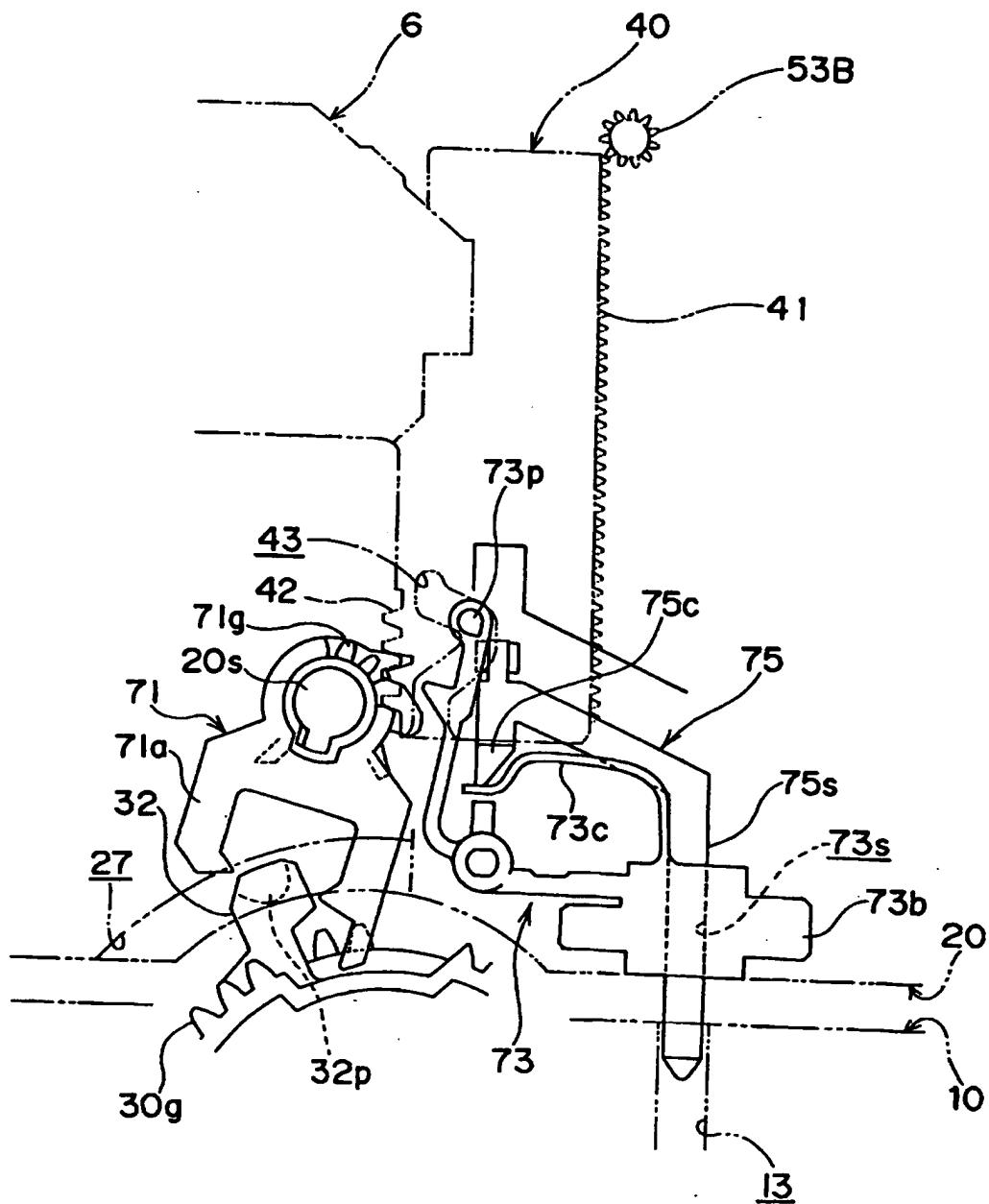
*Fig. 13*

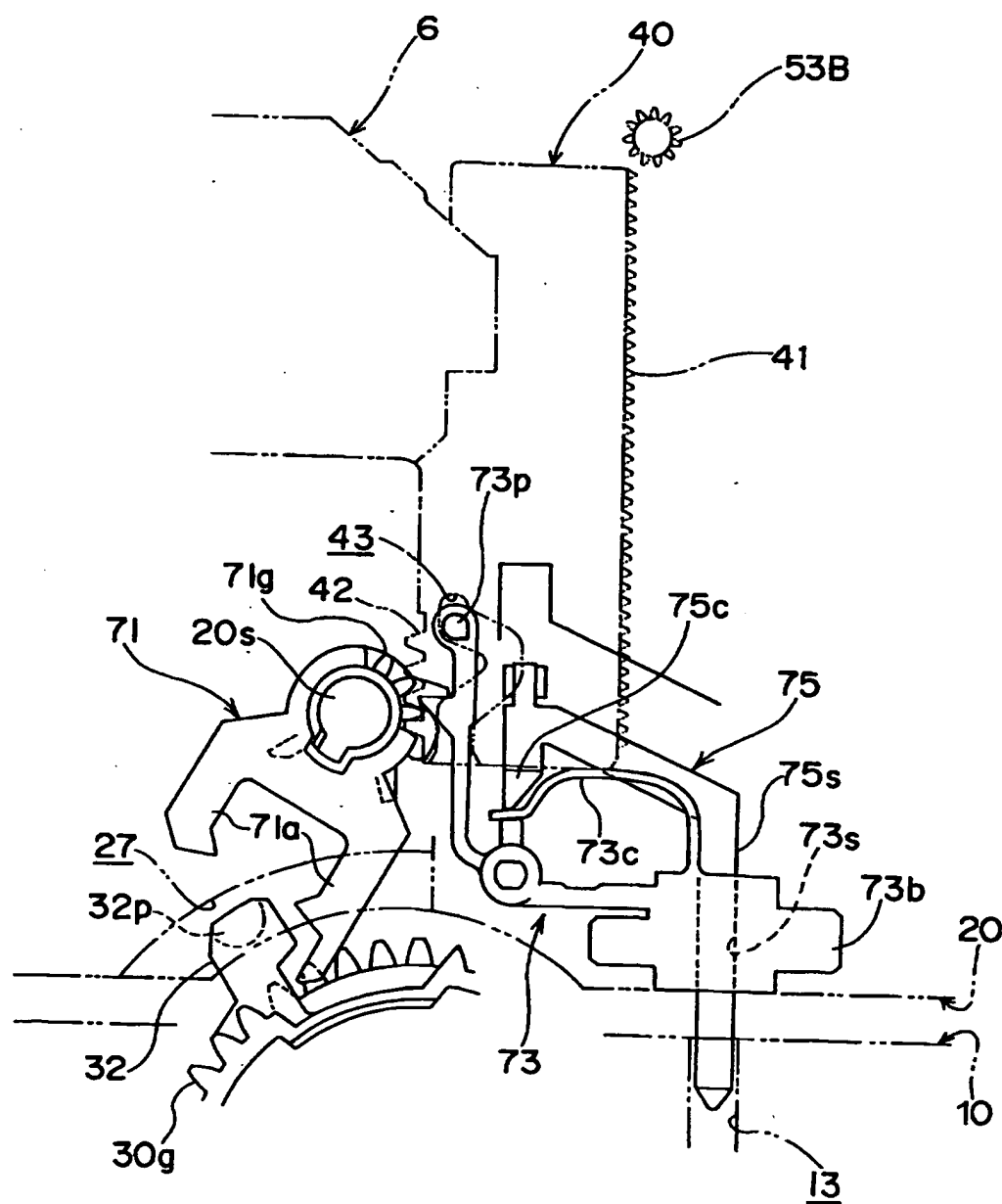
*Fig. 14*

*Fig. 15*



*Fig. 16*

*Fig. 17*

*Fig. 18*

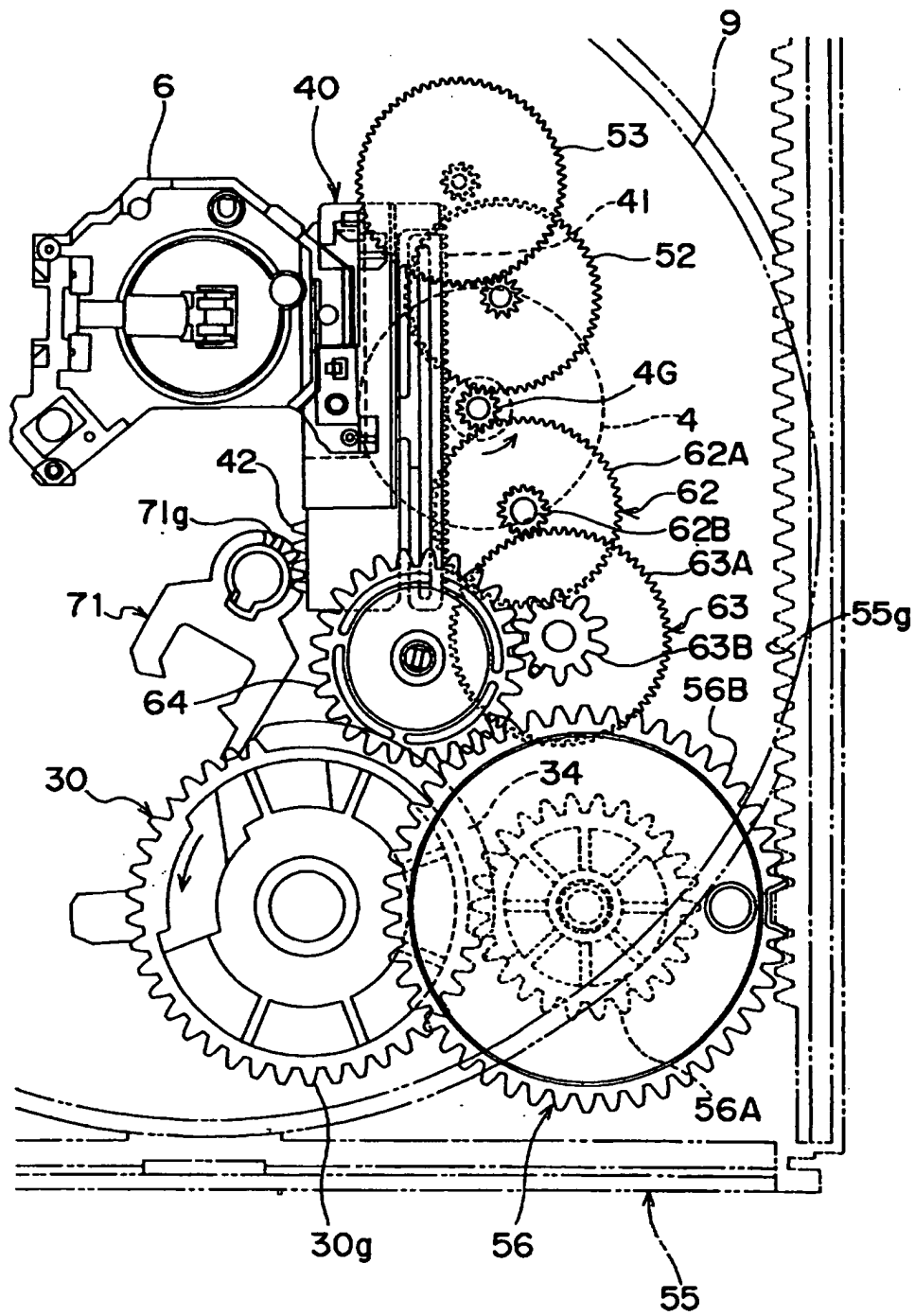
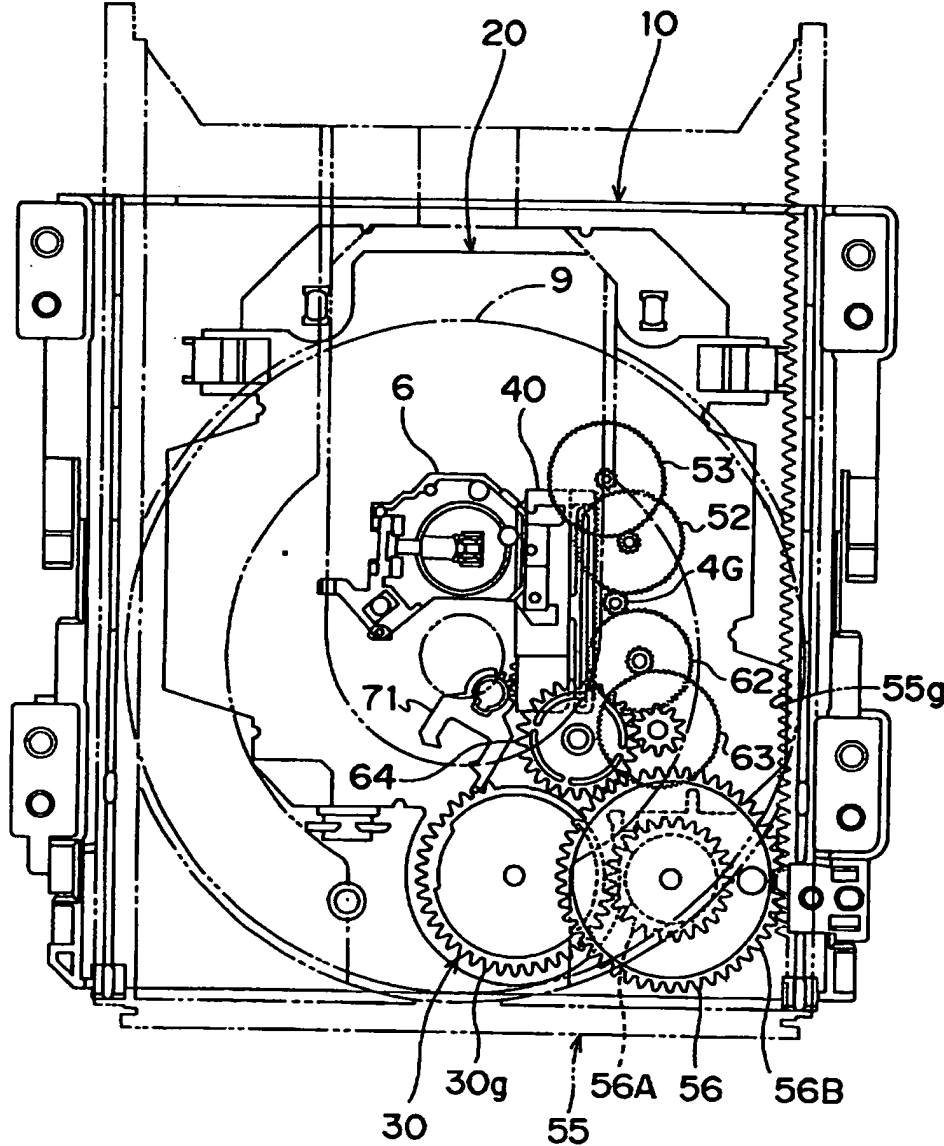
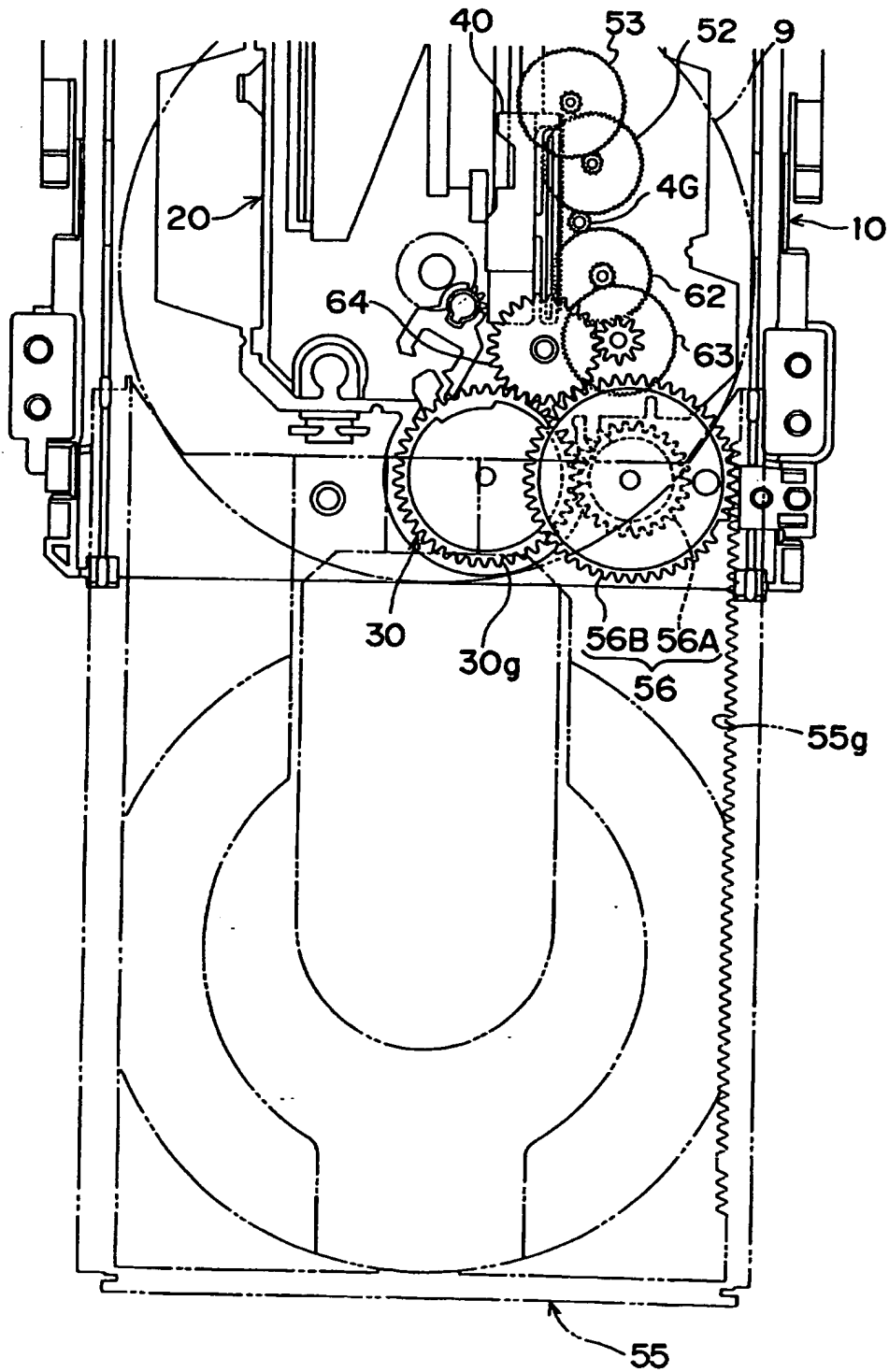
*Fig. 19*

Fig. 20



*Fig. 21*

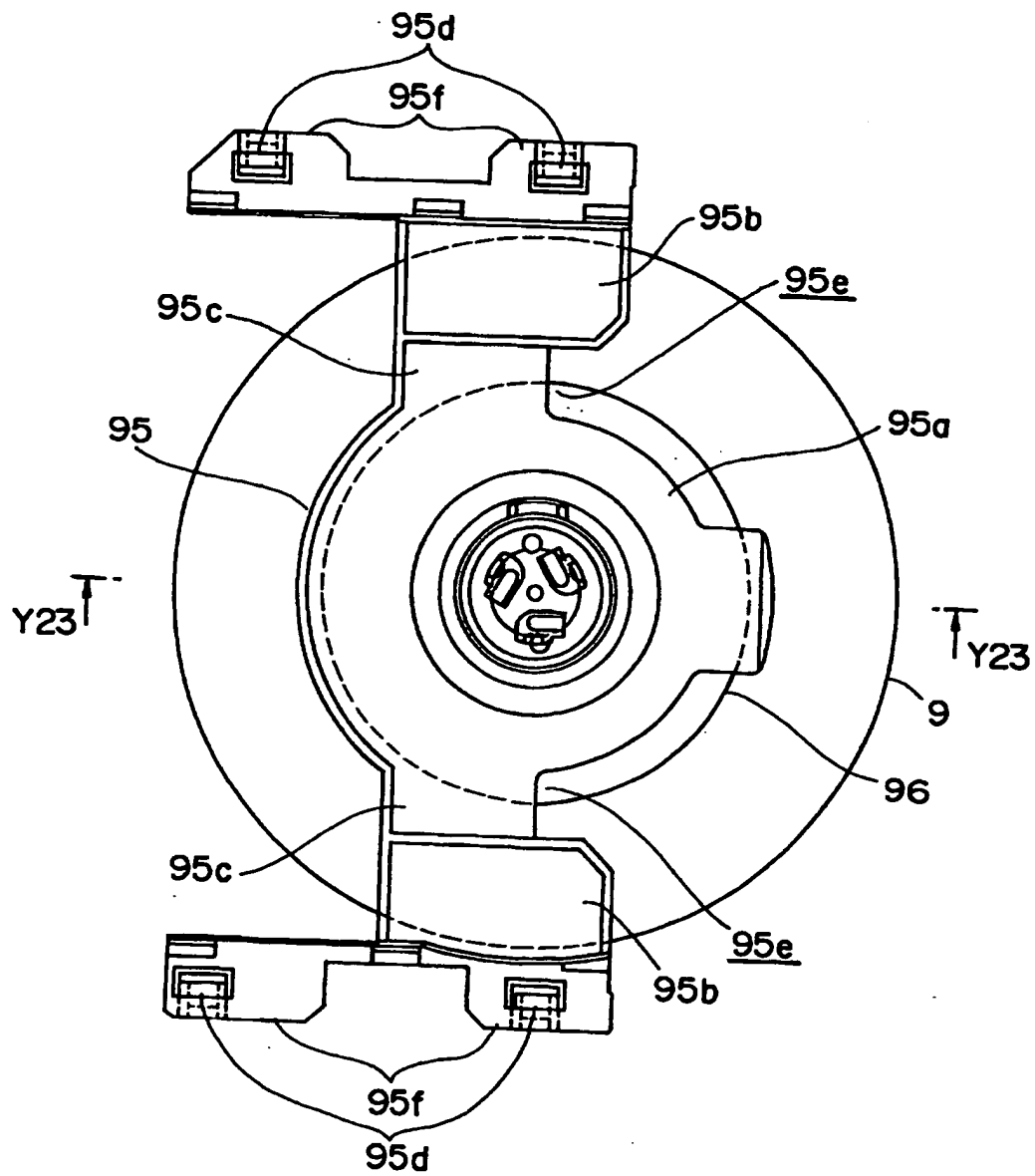
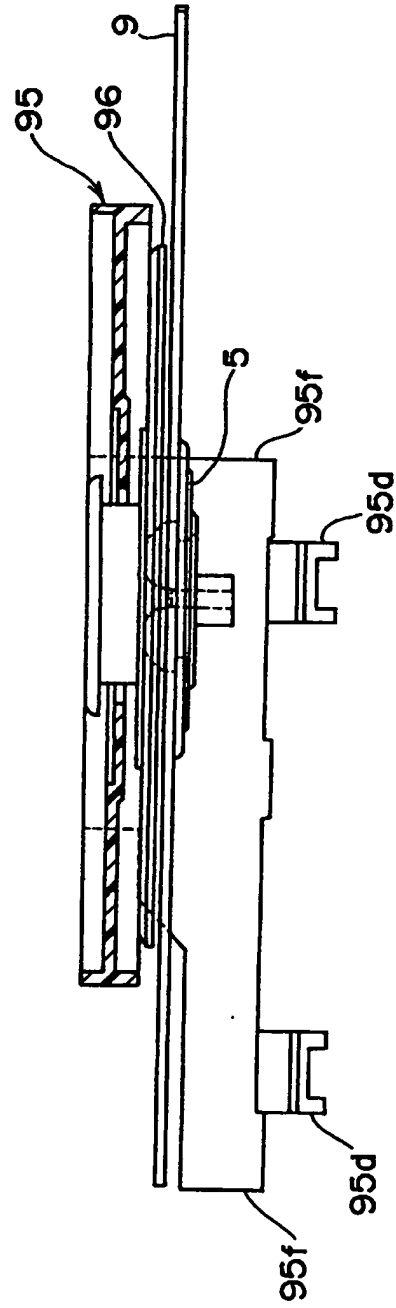
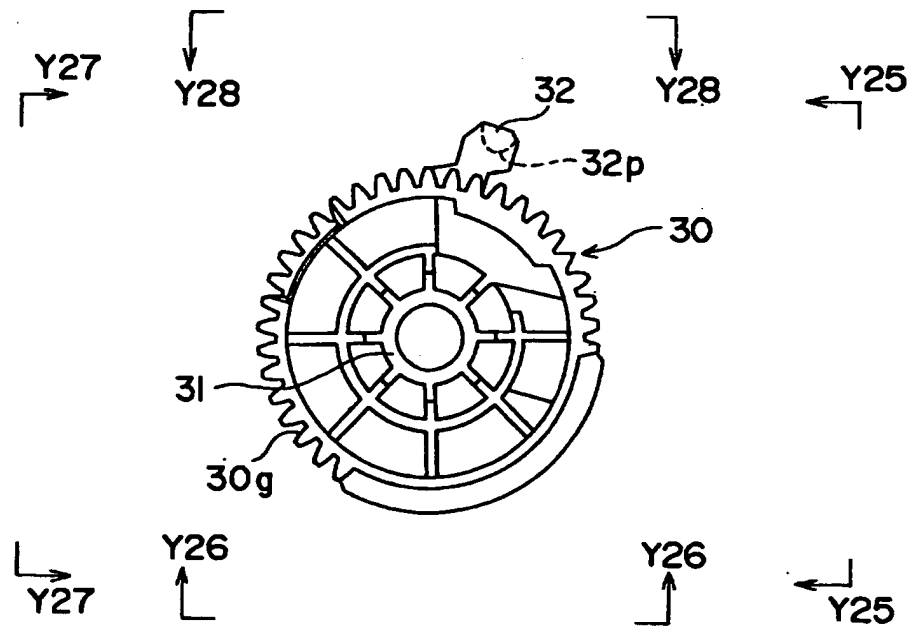
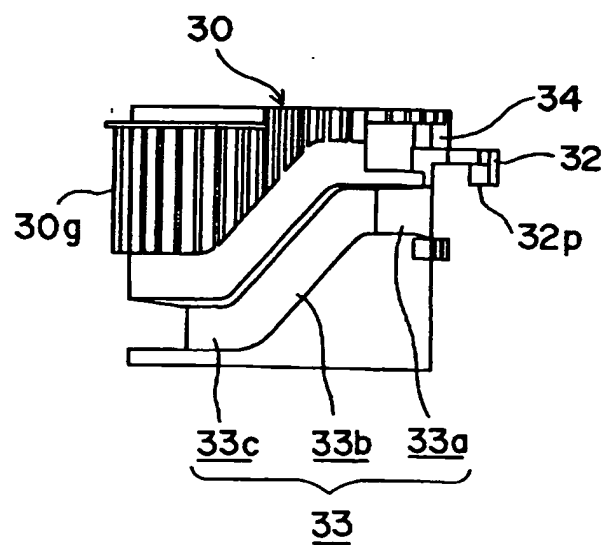
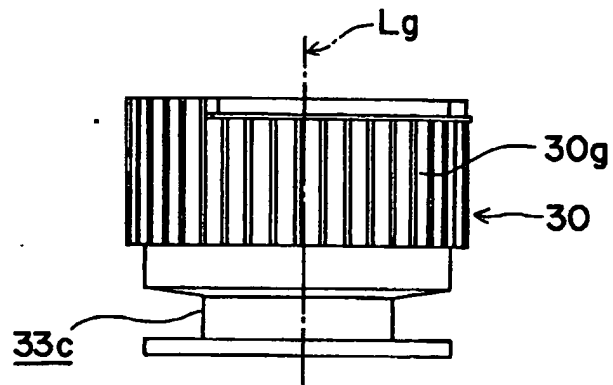
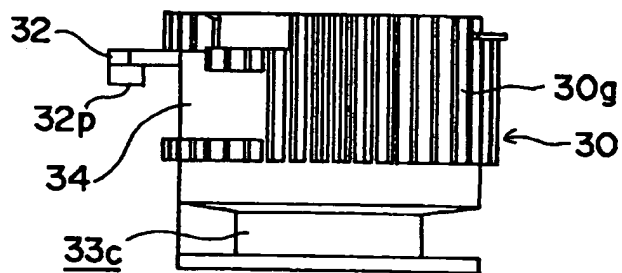
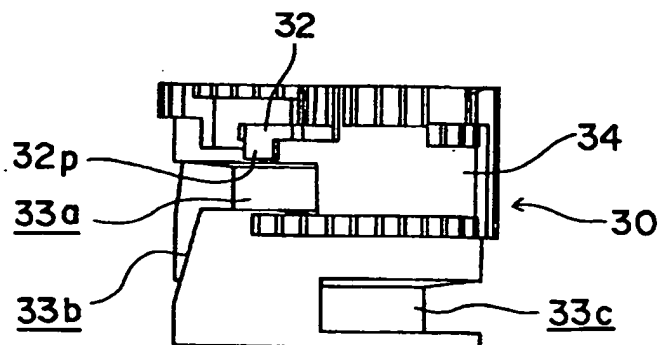
*Fig. 22*

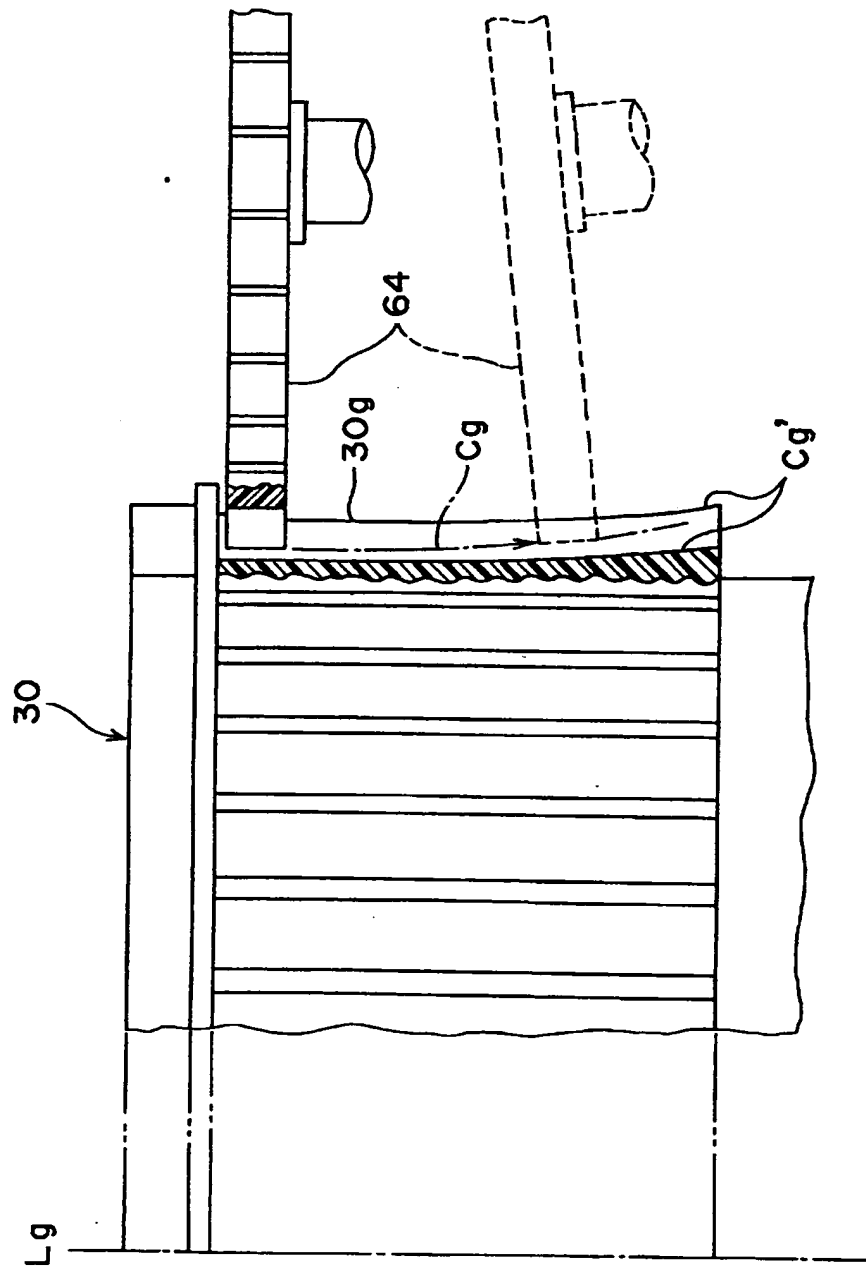
Fig. 23



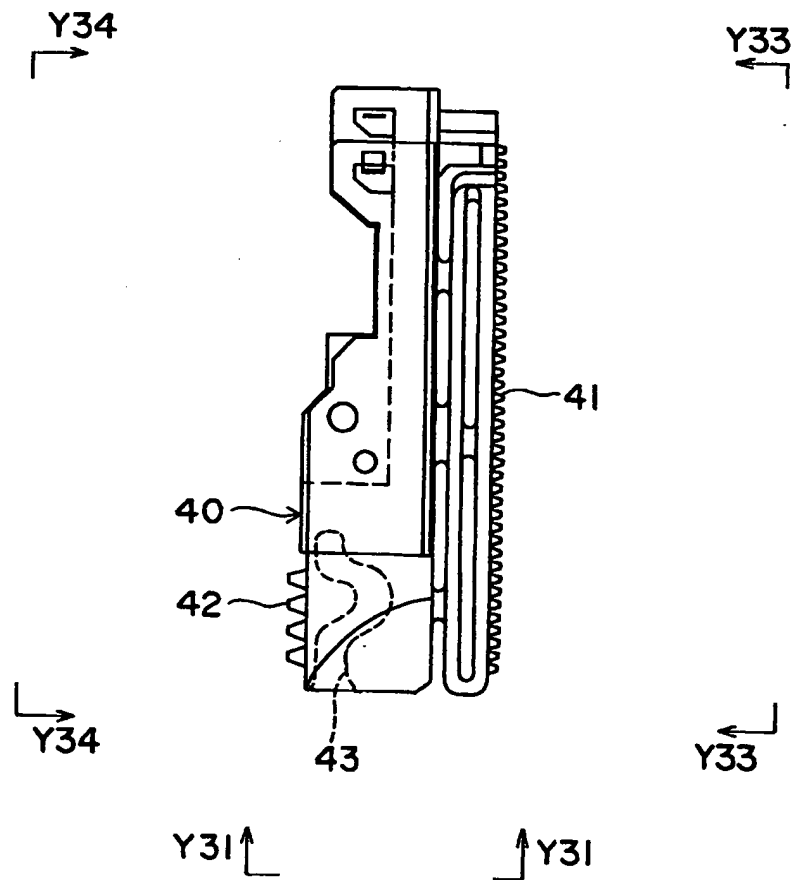


*Fig. 24**Fig. 25*

*Fig. 26**Fig. 27**Fig. 28*

*Fig. 29*

**Fig. 30**



**Fig. 31**

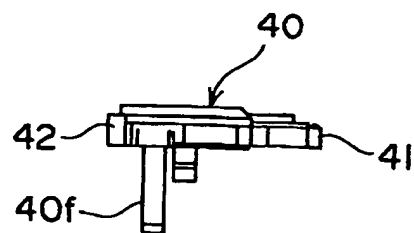


Fig. 32

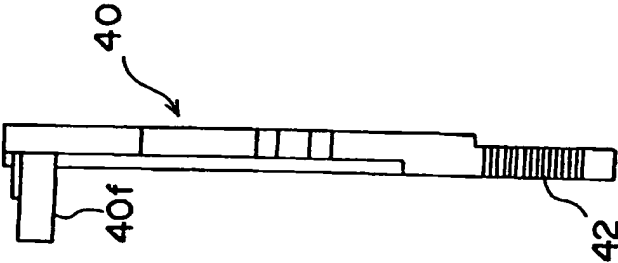


Fig. 33

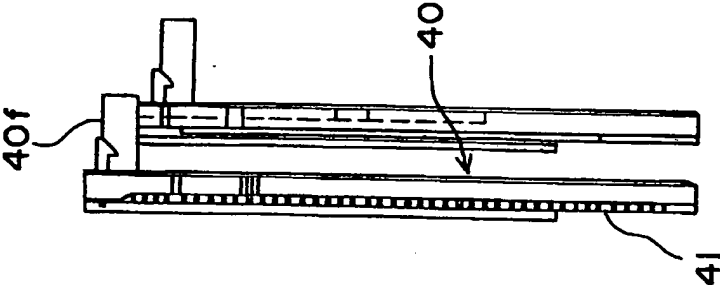


Fig. 34

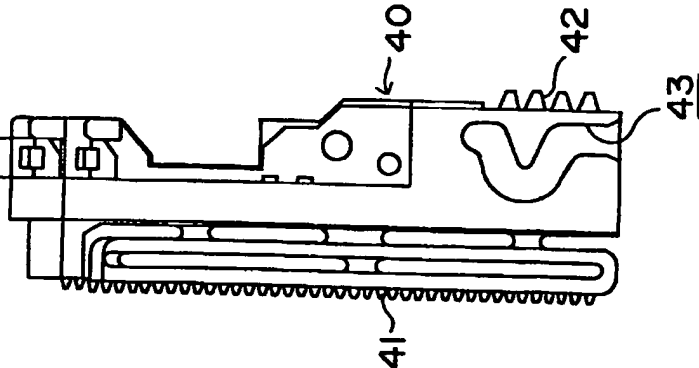


Fig. 37

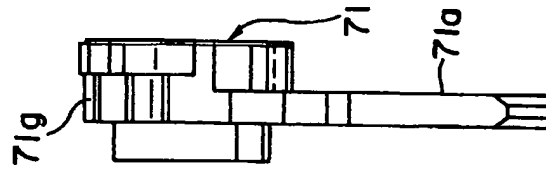


Fig. 36

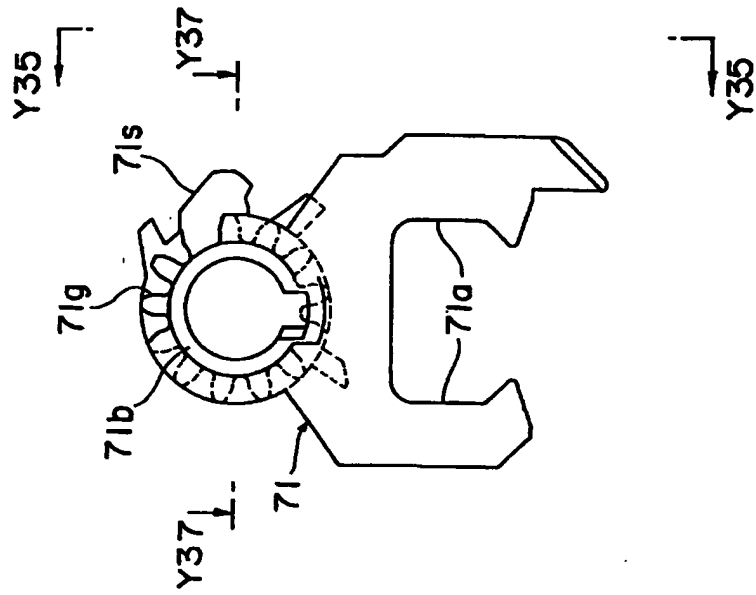
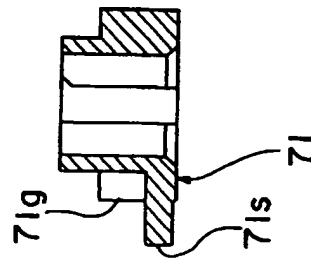


Fig. 35



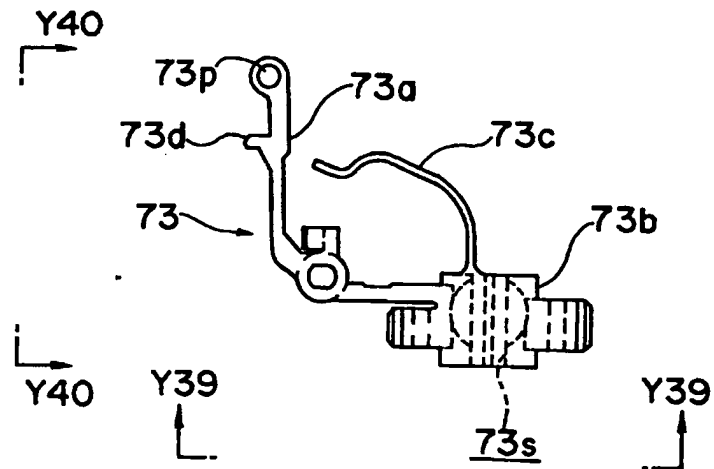
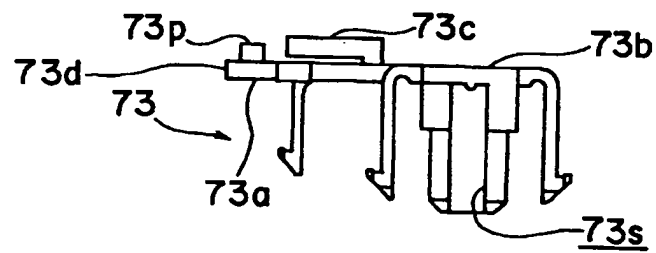
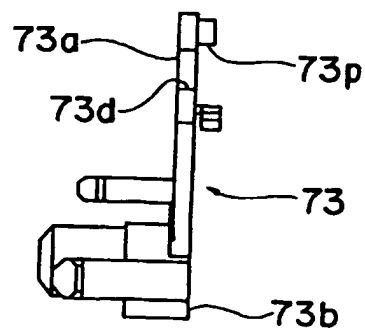
*Fig. 38**Fig. 39**Fig. 40*

Fig. 43

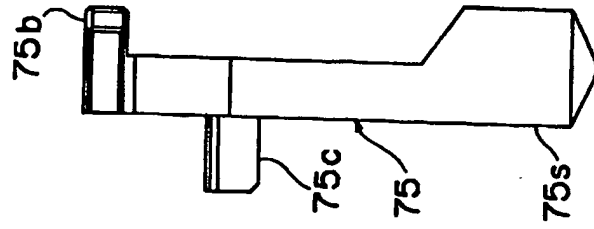


Fig. 42

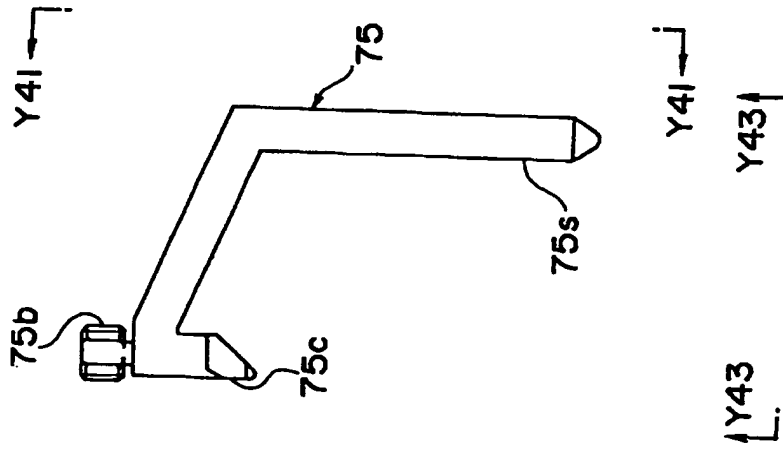
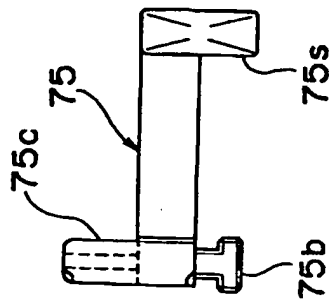


Fig. 41





## Optical disk drive

The present invention relates to an optical disk drive, also referred to herein as simply a disk drive, for recording a data signal and/or reproducing a data signal recorded to an optical disk, also referred to herein as simply a disc, used as a data storage medium. A Compact Disc or CD is exemplary of such data storage media.

5 A disk drive typical of those related to the present invention has an opening on the front panel through which a disk tray opens and closes. After the tray is opened and a disk is loaded onto the tray, the tray is automatically closed, that is, retracted into the disk drive to a turntable.

10 When a disk is loaded into this type of disk drive it is held between the turntable and a clamp and driven at a specific rotational speed so that data signals recorded to the disk can be read by the disk drive, that is recording or reproducing apparatus, during a read operation, for example. More specifically, signals are recorded to tracks within a specific area of the disk, and an optical pickup for signal reading is driven according to the track address of the desired signal so that the desired signal  
25 can be reproduced.

This type of disk drive has three basic operations that require drive motor power: (1) disk loading whereby the tray is driven in two directions between a disk loading/unloading position outside the disk drive at which a disk can be placed on or removed from the tray, and a loading/unloading position inside the disk drive at which the disk is loaded to or unloaded from the turntable; (2) disk driving whereby the turntable is driven to spin a disk; and (3) pickup driving whereby an optical pickup is driven primarily between positions at the outside circumference and inside circumference of the disk.

Typical disk drives according to the related art have also used separate motors, that is, three individual motors, as the drive source for these three operations.

This problem of needing three motors was partially addressed by a disk player (disk drive) as taught in Japanese Utility Model Laid-Open Publication No. 3-49682. This disk player reduced the number of required motors to two, that is, driving a single loading motor in forward and reverse directions for disk loading and unloading, disk chucking, and pickup drive.

A disk drive according to the related art typically comprises a case and a chassis essentially integrated with the case, a turntable fixed to the chassis, and the drive motors. That is, because the vertical

position of the turntable is fixed, the disk must be moved vertically for disk loading and unloading in order to avoid interference with the turntable. In addition, the clamping means (chucking plate) must be driven vertically in order to clamp the disk to the turntable.

A disk holder for lifting the disk is therefore provided at the disk holding surface of the tray in a conventional disk drive. The disk holder is then rotated up or down timed to the tray movement so as to avoid interference between the disk and turntable during disk loading and unloading. A chucking plate is further provided supported by a chucking arm on the fixed chassis so that the chucking plate can rotate and move vertically. This chucking plate is rotated up or down according to the disk loading and unloading timing to either clamp the disk to the turntable or to release the disk. Drive construction and operating the component parts are thus quite complicated and disadvantageous with respect to simplifying drive construction and achieving good stable operation.

Furthermore, all drive parts other than the tray and associated drive system are also provided on the fixed chassis in this conventional disk drive. In addition, these parts are rigidly attached or supported on the fixed chassis. As a result, any impact, shock, or vibration to which the disk player is exposed is also transmitted

directly from the fixed chassis to the various rigidly attached drive parts. These parts are thus easily susceptible to major damage. This design is therefore disadvantageous with respect to improving the durability of the disk drive to the effects of external forces, that is, resistance to shock and vibration.

Rigid attachment of these components to the fixed chassis also makes it necessary to extremely precisely position these components relative to each other. Extremely high precision is therefore required in both parts manufacture and assembly. When the need to mass produce these components is considered, this need for extremely high precision is disadvantageous with respect to increasing productivity.

Considering these problems of the related art, it would therefore be advantageous to provide an optical disk drive whereby the number of motors used can be reduced, construction can be simplified, durability and resistance to shock and vibration can be improved, and productivity can be improved in mass production.

An optical disk drive

according to a first aspect of the present invention has a

turntable for rotatably supporting an optical disc, an optical pickup for writing a data signal to an optical disc rotating on the turntable or reading a data signal recorded to the optical disc, a pickup drive mechanism for moving the optical pickup bidirectionally between the inside circumference side and outside circumference side of the optical disc, and a disk loading mechanism for moving an optical disc bidirectionally between a first position at which the optical disc is above the turntable, and a second position at which the optical disc is outside the disk drive, a first base comprising a base frame of the disk drive, and a second base separate from the first base. The second base is supported to move or swing vertically relative to the first base, and has disposed thereto the turntable and a first motor for rotationally driving the turntable, and the optical pickup and pickup drive mechanism. Disposed on the first and/or second base are: a loading drive mechanism for driving said disk loading mechanism; a second motor that can be driven in forward and reverse directions for supplying drive power to the loading drive mechanism and pickup drive mechanism; and a drive power transfer path switching mechanism for switching the drive power transfer path of the second motor between a path transferring power to the loading drive mechanism and a path transferring power to the pickup drive mechanism.

Thus comprised, moving the optical pickup, raising or lowering the turntable, and moving the optical disc can be substantially continuously performed in this sequence by driving the second motor continuously in a first direction of rotation; these operations can be performed in reverse direction in reverse sequence substantially continuously by driving the second motor continuously in reverse of this first direction of rotation.

10 A separate second base is thus supported on a first base such that the second base can move or swing in a circular path vertically relative to the first base. A single motor (the above-noted second motor) can also be driven continuously forward (in a first direction of rotation) or in the opposite direction to move the optical pickup, raise or lower the turntable, and move the optical disc substantially continuously in this sequence, or substantially continuously in reverse direction in reverse sequence.

20 In an optical disk drive according to a second aspect of the present invention, the second base is disposed inside an opening in the first base, and is supported so that it can swing vertically pivoting around one end thereof relative to the first base; the first base comprises thereon a cam gear disposed near the other end side of the second base, said cam gear having on an outside

25

surface thereof a cam channel for raising and lowering an other end of the second base; and the loading drive mechanism has a loading drive gear set containing a plurality of gears including a final output gear. The said  
5 final output gear of the loading drive gear set engages an outside teeth part of the cam gear to rotate the cam gear and thereby raise or lower said other side of the second base.

In an optical disk drive according to this aspect,  
10 the cam gear is rotated by drive power transferred from the loading drive gear set, and the other end side of the second base is raised or lowered in conjunction with cam gear rotation. As a result, the second base is swung up or down to the first base pivoting around the one end side of  
15 the second base.

In an optical disk drive according to a third aspect of the present invention, the profile of the outside gear part of the cam gear as seen in longitudinal section is an arc or a line approaching said arc. This arc follows  
20 a path of vertical circular motion through which the final output gear of the loading drive gear set travels in conjunction with the swinging movement of the second base.

In this case the final output gear of the loading drive gear set positively engages the outside gear part of  
25 the cam gear when the final output gear swings up or down

in conjunction with the swinging movement of the second base.

5 In an optical disk drive according to a fourth aspect of the present invention, a protrusion is disposed to said other end side of the second base, and this other end side of the second base is positioned vertically as a result of this protrusion engaging a cam channel in the cam gear.

10 In this optical disk drive, vertical positioning of the other end side of the second base to the first base is reliably determined by engagement of the this protrusion and cam channel.

15 In an optical disk drive according to a fifth aspect of the present invention, the disk loading mechanism comprises a tray drive gear for driving the tray on which a disk is placed. When the second base swings downward to a specific position relative to the first base, the outside gear part of the cam gear engages the tray drive gear.

20 In this optical disk drive, the tray is driven after the second base has positively swung down from the first base.

25 In an optical disk drive according to a sixth aspect of the present invention, the pickup drive mechanism comprises a feed rack for moving the optical pickup, and a rack drive gear set comprising a plurality of gears for



driving the feed rack.

After moving the optical pickup to an inside circumference edge position of the data signal recording area of the optical disc, the feed rack can be moved to a specific position farther to the inside circumference side of the disc. By moving to this specific position at the inside circumference side and engaging the drive power transfer path switching mechanism, the second motor drive power transfer path is switched from a path to the pickup drive mechanism to a path transferring power to the loading drive mechanism. By moving from said specific position at the inside circumference side to the outside circumference side of the disc and thereby disengaging from the drive power transfer path switching mechanism, the second motor drive power transfer path is switched from a path transferring power to the loading drive mechanism to a path transferring power to the pickup drive mechanism.

In this optical disk drive the drive power transfer path of the second motor can be automatically switched as a result of the feed rack moving to this specific position to the inside circumference side of the disk after moving the optical pickup to an inside circumference edge of the data signal recording area of the optical disc, and again when the feed rack moves from this specific position toward the outside circumference side of

the disk.

In an optical disk drive according to a seventh aspect of the present invention, a regulating rod retractable from the other end side is disposed to the second base, and a positioning channel that can be engaged by this regulating rod is disposed in the first base. The feed rack engages the regulating rod when it moves from the one end side to the other end side of the second base and reaches a specific position. The regulating rod protrudes from the other end side of the second base and fits into said positioning channel when the feed rack moves further toward the other end side after engaging the regulating rod, thereby positioning the second base to the first base in a lateral direction perpendicular to the direction of feed rack travel.

In this optical disk drive, the regulating rod is driven to project from the other end side of the second base as result of the feed rack moving beyond a specific position to the other end side. The regulating rod thus fits into the positioning channel in the first base, and thereby determines the lateral position of the second base to the first base perpendicular to the direction of feed rack travel.

In an optical disk drive according to an eighth aspect of the present invention, the cam gear comprises a

hook part projecting to the outside, and the second base comprises on a surface thereof a curved channel parallel to an outside part of the cam gear. The hook part engages this curved channel to position the second base to the first base in the direction of feed rack travel.

As a result of the cam gear hook part engaging this curved channel, the second base is positioned to the first base in the direction of feed rack travel.

In an optical disk drive according to a ninth aspect of the present invention, an elastic damping member is disposed to a support part for supporting said one end side of the second base to the first base, and to a support part for supporting the cam gear to the first base. The second base is thus supported in a floating state on the first base within the range of elasticity of the damping members.

The second base is therefore not rigidly supported on the first base, but is instead supported so as to float on the first base within limits determined by the flexibility of the damping members.

Particular embodiments of the invention will now be described with reference to the accompanying drawings; in which:-

Fig. 1 is an overall perspective view of the assembled optical disk drive according to a preferred embodiment of the present invention;

Fig. 2 is an exploded view of the disk drive shown in Fig. 1;

Figs. 3 and 4 are enlarged views of parts of Fig. 2;

Fig. 5 is a plan view of the traverse base and drive base of the optical disk drive shown in Fig. 1;

Fig. 6 is a partial side section view showing a typical support structure holding the traverse base to the drive base;

Fig. 7 is a typical partial side section view showing the traverse base inclined to the drive base;

Fig. 8 is an enlarged vertical section view of the floating bushing fit to the traverse base;

Fig. 9 to Fig. 13 are a sequence of plan views showing the operation of a drive mechanism in the optical disk drive shown in Fig. 1;

Fig. 14 to Fig. 18 are a sequence of enlarged plan views showing the drive power transfer path switching operation of the drive mechanism in the optical disk drive shown in Fig. 1;

Fig. 19 is an enlarged plan view showing the engagement of the tray and tray drive gear;

Fig. 20 is a plan view of the optical disk drive with the tray stored inside the drive;

5 Fig. 21 is a plan view of the optical disk drive with the tray moved outside the drive;

Fig. 22 is an enlarged plan view showing the disk clamping mechanism of the optical disk drive;

10 Fig. 23 is a section view through line Y23-Y23 in Fig. 22;

Fig. 24 is a plan view of the cam gear of this drive mechanism;

Fig. 25 is a side section view through line Y25-Y25 in Fig. 24;

15 Fig. 26 is a side section view through line Y26-Y26 in Fig. 24;

Fig. 27 is a side section view through line Y27-Y27 in Fig. 24;

20 Fig. 28 is a side section view through line Y28-Y28 in Fig. 24;

Fig. 29 is a partial vertical section view showing the tooth profile of the cam gear;

Fig. 30 is a plan view of the feed rack of the drive mechanism;

25 Fig. 31 is a side section view of the feed rack

through line Y31-Y31 in Fig. 30;

Fig. 32 is a back view of the feed rack;

Fig. 33 is a section view of the feed rack  
through line Y33-Y33 in Fig. 30;

5 Fig. 34 is a section view of the feed rack  
through line Y34-Y34 in Fig. 30;

Fig. 35 is a section view of the trigger lever  
through line Y35-Y35 in Fig. 36;

10 Fig. 36 is a plan view of the trigger lever of  
the drive mechanism;

Fig. 37 is a vertical section view of the trigger  
lever through line Y37-Y37 in Fig. 36;

Fig. 38 is a plan view of a rocker lever of the  
drive mechanism;

15 Fig. 39 is a side view of the rocker lever  
through line Y39-Y39 in Fig. 38;

Fig. 40 is a side view of the rocker lever  
through line Y40-Y40 in Fig. 38;

20 Fig. 41 is a side view of the rocker lever  
through line Y41-Y41 in Fig. 42;

Fig. 42 is a plan view of the rocker lever of the  
drive mechanism; and

Fig. 43 is a side view of the rocker lever  
through line Y43-Y43 in Fig. 42.

Fig. 1 is an overall perspective view of the assembled optical disk drive according to a particular embodiment of the present invention. Fig. 2 is an exploded view of the disk drive shown in Fig. 1, and Figs. 3 and 4 are enlarged views of parts of Fig. 2.

It should be noted that optical disk drive, disk drive, and simply drive are used synonymously throughout this specification.

As will be known from these figures, an optical disk drive 1 according to this particular embodiment comprises a drive base 10 as the installation base for major components of the drive 1, and a traverse base 20 as the support base for supporting the major part of the disk drive's drive mechanism.

The overall shape of the drive base 10 is a substantially square frame when seen in plan view. The traverse base 20 is assembled to an internal space 10H in the drive base 10.

It should be noted that the drive base 10 and traverse base 20 correspond respectively to the first base and second base in the accompanying claims.

A disc used as the data storage medium, such as a

Compact Disc (CD), is placed on a tray 55 in this disk drive 1. The tray 55 transports a disk placed thereon bidirectionally along the frame of drive base 10. The path of the tray 55 is diagonal as seen in Fig. 1 and Fig. 2 and indicated by the arrow in Fig. 2. Thus, when a disk is removed from inside the disk drive 1, that is, is ejected, the tray 55 travels diagonally downward to the left as seen in Fig. 1 and Fig. 2, and when the disk is loaded from outside into the disk drive 1, that is, is inserted, the tray 55 travels diagonally upward to the right as seen in Fig. 1 and Fig. 2.

It should be noted that the side of the disk drive 1 from which the disk, that is, the tray 55, is removed from inside the disk drive 1 (the diagonal lower left side in Figs. 1 and 2) is hereafter referred to as the front of the drive 1, and the side of the drive 1 to which the disk is inserted (the diagonal upper right side in Figs. 1 and 2) is hereafter referred to as the back of the drive 1. The top and bottom of the drive 1 as seen in Figs. 1 and 2 are also referred to hereafter as the top and bottom sides.

A pair of right and left traverse base support studs 11 is disposed vertically at the back of the drive base 10, that is, at the top right in Fig. 1 and Fig. 2. A notch 21 is formed at each back corner of the traverse base.



20. A elastic, typically rubber, bushing 29 (floating bushing) is fit into each notch 21. By fitting these bushings 29 on the above-noted traverse base support studs 11, the back of the traverse base 20 is supported such that it can pivot in a vertical direction to the drive base 10 centering on a horizontal line 1h (see Fig. 5) between the centers of the tips of the right and left traverse base support studs 11.

The back of the traverse base 20 is also supported by means of the right and left bushings 29 so that the traverse base 20 can float relative to the drive base 10 within a specific range. This range is that enabled by the flexibility of the bushings 29. It should be noted that the right and left bushings 29 are not shown in Fig. 5 so that the traverse base support studs 11 and notches 21 can be clearly seen.

These bushings 29 are described in detail next with reference to Fig. 8. The bushings 29 are an integral hollow body molding with one end closed and the other end open. Each bushing 29 also has relatively large diameter first and second damping parts 29a and 29b in sequence along the long axis of the bushing 29, and a relatively small diameter fitting part 29c (first fitting part) between the two damping parts.

This first fitting part 29c thus forms a

constricted neck between damping parts 29a and 29b, and is the part that is fit to the traverse base 20 as the first member to be supported in a floating state by the floating bushings 29. More specifically, the bushing 29 is installed to a notch 21 in a rear corner of the traverse base 20 by fitting the outside circumference of the first fitting part 29c into the hole part of a bushing mounting flange 21b in the notch 21.

A second fitting part 29d for closing the cavity inside the floating bushing 29 is integrally formed to the terminal side of the first damping part 29a. This second fitting part 29d is the part that is fit to the drive base 10, which is the second member to be floatably supported by the bushings 29. More specifically, this second fitting part 29d is fit to the end 11d of the traverse base support stud 11.

The terminal side of the second damping part 29b is open. The traverse base support stud 11 is inserted to the floating bushing 29 from this opening. The terminal part of the second damping part 29b contacts the bushing support surface 10f of the drive base 10.

Preferably, the back of the traverse base 20 is assembled to the drive base 10 by way of bushings 29 such that the terminal part of the second damping part 29b contacts bushing support surface 10f with a certain

flexibility when in a normal state. As used herein this normal state is that in which only the normal weight of the traverse base 20 and components mounted thereon acts on the bushings 29.

5           When vibration is applied to the disk drive 1 when the drive 1 is in use or during manufacture and force is thus applied causing relative movement between the drive base 10 and traverse base 20, the damping action accompanying compressive deformation within the flexibility  
10 limits of the second damping part 29b effectively absorbs vibration components from the downward movement (that is, in the direction in which the bushing mounting flange 21b approaches the bushing support surface 10f) of the back of the traverse base 20.

15           It should be noted that contact between the terminal end of the second damping part 29b and the bushing support surface 10f in this normal state is not necessarily a prerequisite for achieving this vibration damping effect from the second damping part 29b. A gap between this  
20 terminal end and the bushing support surface 10f simply reduces the vibration damping effect an amount equivalent to the gap, and when the relative movement between the drive base 10 and traverse base 20 exceeds this gap, the vibration damping effect is equivalent to how much this  
25 relative movement exceeds the gap.

When the back of the traverse base 20 moves downward, the bushing mounting flange 21b moves away from the end 11d of traverse base support stud 11, the top of the second fitting part 29d becomes suspended on the end 11d of traverse base support stud 11, and the first damping part 29a is stretched and deformed within its flexibility limit.

Vibration can therefore be absorbed both by the damping effect of the stretch deformation of the first damping part 29a and the damping effect of the compressive deformation of second damping part 29b. Extremely effective vibration absorption can thus be achieved.

The second fitting part 29d is part of the typically rubber floating bushing 29 and is therefore quite flexible. The flexibility of this second fitting part 29d therefore makes it possible to further improve the vibration damping effect and noise suppression when a force causing relative movement between the drive base 10 and traverse base 20 is applied.

It should be further noted that the second fitting part 29d of the floating bushing 29 can be formed so as to not completely close the one end (top) of the internal cavity of the floating bushing 29. More specifically, the second fitting part 29d can have an opening insofar as the end 11d of the traverse base support

stud 11 does not pass completely through said opening when a force lifting the traverse base support stud 11 toward the opening is applied.

Vibration components whereby the back of the traverse base 20 moves upward (that is, such that the bushing mounting flange 21b moves closer to the end 11d of traverse base support stud 11) can be effectively absorbed by the damping effect accompanying the compressive deformation of the first damping part 29a within the flexibility limits of the first damping part 29a.

Lateral vibration components parallel to the base surface, such as vibration components in the front-back direction or side to side direction of the traverse base 20, are absorbed by lateral deformation of the floating bushing 29 within its flexibility limit.

The end 11d of traverse base support stud 11 is preferably comprised such that when seen in a vertical section view the shape of the outside edge is part of a circle. In this case, the shape of the inside edge of the second fitting part 29d of the floating bushing 29 as seen in a vertical section view is also part of a circle.

When thus comprised, the second fitting part 29d, that is, the entire floating bushing 29, can move circularly around center C11 of the traverse base support stud end 11d. The axis of movement Lh (see Fig. 5) when the

traverse base 20 pivots up or down relative to the drive base 10 is a straight line joining centers C11 of the ends 11d of the right and left traverse base support studs 11.

Yet further preferably, there is a specific gap  
5 between the inside circumference of the second fitting part 29d and the outside circumference of the end 11d of traverse base support stud 11, and a plurality of protrusions 29e are formed in the second fitting part 29d. These protrusions 29e are directed toward the center of the  
10 inside circumference of second fitting part 29d, and therefore to the center C11 of support stud end 11d when the traverse base support stud 11 is fit into the floating bushing 29.

That is, second fitting part 29d of floating  
15 bushing 29 is fit onto the end 11d of traverse base support stud 11 through intervening protrusions 29e, and a specific gap is thus maintained between the second fitting part 29d and end 11d. As a result, the second fitting part 29d can move extremely smoothly circularly to the end 11d of  
20 traverse base support stud 11.

The floating bushing 29 thus comprises first and second damping parts 29a and 29b, and first and second fitting parts 29c and 29d. It is therefore possible to provide a simple, space-saving, low cost floating means  
25 that can support the entire weight of the traverse base 20,

and effectively absorb vibration while preventing the traverse base 20 from slipping vertically out of place, when the traverse base 20 vibrates.

Furthermore, by providing a center of rotation part, an accurate center of circular movement can be assured without providing another center for circular movement.

As will also be known from Fig. 4 and Fig. 5, a recess 12 of which the shape of the perimeter is part of a circle is formed at the front edge part of internal space 10H in drive base 10. A spindle 12s is vertically disposed in the bottom center of this recess 12. The center boss 31 of a substantially cylindrical cam gear 30 is fit so that it can rotate freely on this spindle 12s. A coil spring 39 (floating spring) is disposed between the bottom of this cam gear 30 and the bottom of recess 12 in drive base 10. The center boss 31 of the cam gear 30 is passed over the spindle 12s, and a set screw 37 is screwed through a flexible collar 38 (floating collar) into the end of the spindle 12s.

The cam gear 30 is therefore housed in recess 12 of drive base 10 with the top and bottom held between elastic members 38 and 39, that is, with the bottom of the cam gear 30 supported by coil spring 39 and the top held by the floating collar 38. As a result, the cam gear 30 is

supported on the drive base 10 in a manner enabling the cam gear 30 to float (in a floating state) within specific limits, that is, within the flexibility limits of the floating collar 38 and floating spring 39.

5           It should be noted that the above-noted floating collar 38, floating spring 39, and right and left floating bushings 29 correspond to the damping members noted in the accompanying claims.

10           It should be further noted that the floating bushing 29 and floating collar 38 shall not be limited to rubber materials. For example, a soft resin or other suitable material with a specific flexibility can be alternatively used.

15           The cam gear 30 is described in detail next with reference to Figs. 24 to 29. The cam gear 30 comprises on its outside surface a plurality of teeth 30g (external teeth) parallel to the long axis Lg of the cam gear 30, and a cam channel 33 having top and bottom horizontal channels 33a and 33c, and diagonal channel 33b.

20           There is also a smooth part 34 in which there are no teeth 30g on the outside surface of the cam gear 30. A protrusion 20P for slideably engaging the cam channel 33 is also provided at the front edge of the traverse base 20 (see Fig. 2 and Fig. 3). This protrusion 20P engages the  
25   cam channel 33 to support the front of the traverse base 20



by way of cam gear 30 on the drive base 10.

As shown in Fig. 6 and Fig. 7, the traverse base 20 is thus supported at the back by way of bushings 29 and at the front by way of cam gear 30 supported on floating collar 38 and floating spring 39 so that it floats within specific limits on the drive base 10. Note that these limits are determined by the flexibility of the floating bushing 29, floating collar 38, and floating spring 39.

The traverse base 20 is thus not rigidly supported on the drive base 10 in the manner of a disk drive according to the related art, but is supported so that it can float on the drive base 10 within the range of the flexibility of the supporting damping members, that is, the floating bushing 29, floating collar 38, and floating spring 39. The damping members 29, 38, and 39 can therefore absorb an impact, shock, or vibration applied to the disk drive 1, thereby preventing the force of the impact or vibration from being directly transmitted from the drive base 10 to components on the traverse base 20. As a result, a disk drive 1 with improved durability and resistance to impact and vibration can be achieved.

Furthermore, by supporting the traverse base 20 so that it floats on the drive base 10 within the range of the flexibility of the damping members 29, 38, and 39, it is possible to adjust the relative positions of components

on the drive base 10 and traverse base 20 within the floating range of the traverse base 20. Compared with a conventional disk drive in which the components are rigidly supported, a disk drive according to the present invention  
5 therefore also requires less precision in parts manufacture and assembly, and productivity can therefore be improved in the manufacturing process.

As shown in Fig. 2 and Fig. 3, first and second electric motors 3 and 4, and a circuit board 2 comprising a  
10 control circuit for controlling driving motors 3 and 4, are also fastened to the bottom of drive base 10.

A turntable 5 on the top of which is placed a disc 9 (see Figs. 5 to 7) is also disposed above the drive base 10. This turntable 5 is linked to the output shaft 3s  
15 (see Fig. 3) of the first motor 3 (spindle motor). An optical pickup 6 for writing a data signal to or reading a recorded data signal from the disc 9, and other drive components for operating the disk drive 1, are also disposed on top of drive base 10.

20 These drive mechanisms are described next below.

As will be understood from Fig. 3 and Fig. 5, a front to back (top to bottom) opening 20H is provided in traverse base 20. A pair of pickup guide channels 22 and 23 for guiding front to back travel of the optical pickup 6 is  
25 provided on the sides of this opening 20H. The turntable 5

is preferably positioned near the front end of the pickup guide channels 22 and 23 and opening 20H, or even forward of this position.

5 The optical pickup 6 is supported so that it can slide front to back on the traverse base 20 by slideably engaging right and left legs 6f in the pickup guide channels 22 and 23. It should be noted that a flexible connection means, such as a flexible ribbon cable, for electrically connecting the optical pickup 6 and circuit  
10 board 2 is passed through the opening 20H.

A rail member 24 (guide rail) extending parallel to the guide channel is provided beside one of the pickup guide channels 22 and 23, and a rack member 40 (feed rack) for sliding lengthwise to the guide rail 24 is engaged with  
15 the guide rail 24. Note that in Fig. 3 and Fig. 5 the guide rail 24 is provided on the right beside guide channel 23.

One end (the right end in Fig. 3 and Fig. 5) of the optical pickup 6 is linked to the feed rack 40 by a screw 49 (see Fig. 3). As a result, the optical pickup 6  
20 can be moved bidirectionally front and back guided by the pickup guide channels 22 and 23 by sliding the feed rack 40 along the guide rail 24.

As shown in detail in Figs. 30 to 34, teeth 41 (driven rack part) are formed along substantially the full  
25 length on one side of the feed rack 40 (the right side in

Fig. 3 and Fig. 5). A length of teeth 42 (transfer path switching rack) is also formed on the other side at the front of the feed rack 40.

It should be noted that arm 40f projecting from the back of the feed rack 40 engages the pickup guide channel 23, and limits movement of the feed rack 40 to the back by striking and stopping at the back wall of the pickup guide channel 23 when the feed rack 40 travels to the back (upward in Fig. 5).

A gear set 51 (rack drive gear set) <sup>Fig. 9</sup> comprising a group of gears is disposed to the traverse base 20 to drive the feed rack 40 and move the optical pickup 6 bidirectionally front and back.

As shown in detail in Figs. 9 to 13, this gear set 51 comprises: a motor gear 4G fastened to the output shaft 4s of the second motor 4; a first traverse gear 52 having a large diameter input gear 52A (first traverse input gear) for engaging the motor gear 4G, and a small diameter output gear 52B (first traverse output gear) integrally disposed to the top of the input gear 52A; and a second traverse gear 53 having a large diameter input gear 53a (second traverse input gear) for engaging the first traverse output gear 52B, and a small diameter output gear 53B (second traverse output gear) integrally disposed to the bottom of the second traverse input gear 53a. The

second traverse output gear 53B engages the driven rack  
part 41 of the feed rack 40.

When the second motor 4 is driven and the motor  
gear 4G turns at a specific speed in, for example, the  
5 counterclockwise direction as seen in Fig. 9 to Fig. 13  
(corresponding to the first direction of rotation in the  
accompanying claims of this invention), motor rotation is  
speed reduced at a specific reduction ratio and is  
transferred to the output side by the gear set 51 so that  
10 the final output gear 53B (second traverse output gear)  
turns counterclockwise at a reduced speed.

This causes the feed rack 40 to travel at a  
predetermined speed along the guide rail 24 to the front  
(to the bottom as seen in Figs. 9 to 13). When the second  
15 motor 4 is driven in the direction opposite that described  
above, and feed rack 40 also travels in the opposite  
direction.

It is therefore possible by switching the forward  
and reverse direction of second motor 4 operation to change  
20 the direction in which the feed rack 40, and therefore the  
optical pickup 6, travels, and the feed rack 40 and optical  
pickup 6 can therefore be driven bidirectionally forward  
and back.

The feed rack 40 and gear set 51 form the basic  
25 optical pickup drive mechanism, equivalent to the optical

pickup drive mechanism of the accompanying claims, whereby the optical pickup 6 is moved in two directions between the inside circumference and outside circumference of the disc 9. The pickup guide channels 22 and 23 and guide rail 24 also assist driving the optical pickup 6.

A tray drive gear 56 for moving the tray 55 between an unloading position at the front of the disk drive 1 so that a disc can be place on or removed from the tray 55, and a loading position inside the disk drive 1 at which a disk is loaded to or unloaded from the turntable 5, is provided at the front of the drive base 10.

It should be noted that this loading position and unloading position are equivalent to the first position and second position, respectively, in the accompanying claims.

This tray drive gear 56 comprises a large diameter output gear 56B for engaging the tray rack teeth 55g provided on the back of the tray 55 (see Fig. 19 to Fig. 21), and a small diameter input gear 56A below the output gear 56B. The tray drive gear 56 is positioned beside the cam gear 30 such that the input gear 56A engages the outside teeth 30g of the cam gear 30.

The tray 55, tray rack teeth 55g, and tray drive gear 56 form a disk loading mechanism, equivalent to the disk loading mechanism in the accompanying claims, for carrying a disc 9 between the turntable 5 loading position

(first position) and the unloading position (second position) outside the disk drive 1.

A loading drive gear set 61 (see Fig. 9 to Fig. 13) for moving the tray 55 between the disc 9 unloading position and loading position is provided on top of the traverse base 20.

This loading drive gear set 61 comprises: motor gear 4G attached to the output shaft 4s of the second motor 4; a first loading gear 62 having a large diameter first loading input gear 62A for engaging the motor gear 4G, and a small diameter first loading output gear 62B disposed integrally to the top of the first loading input gear 62A; a second loading gear 63 having a large diameter second loading input gear 63A for engaging the first loading output gear 62B, and a small diameter second loading output gear 63B disposed integrally to the top of the second loading input gear 63A; and a large diameter third loading gear 64 for engaging the second loading output gear 63B. This third loading gear 64 engages teeth 30g of the cam gear 30.

The profile of teeth 30g of the cam gear 30 when seen in vertical section, or more preferably in side view as shown in Fig. 29, is curved. When the traverse base 20 and cam gear 30 are assembled into the drive base 10 with the traverse base 20 pivoting at the back edge thereof so

as to move circularly up and down relative to the drive base 10 (see Fig. 6 and Fig. 7), the curve of the tooth profile is part of the arc  $Cg'$  tracing the circular path  $Cg$  of the front edge of the third loading gear 64.

5        The third loading gear 64 on the traverse base 20 and teeth 30g of the cam gear 30 can therefore reliably and smoothly engage even when the traverse base 20 has swung to a position at an angle to the drive base 10 (indicated by the dotted line in Fig. 29 and shown in Fig. 7). It should  
10       be noted that the profile of teeth 30g in vertical section can be a straight line at an incline to the long axis  $Lg$  of the cam gear 30 and approaching curve  $Cg'$ .

It should be further noted that the second loading gear 63 is not shown in Fig. 6 and Fig. 7 to  
15       provide a clearer view of the third loading gear 64 engaging teeth 30g of cam gear 30.

As thus described, the profile in vertical section of the teeth 30g of cam gear 30 is an arc following the circular path of the third loading gear 64, that is,  
20       the last output gear of the loading drive gear set 61, as the gear 64 moves circularly up or down in conjunction with the circular movement of the traverse base 20, or is a straight line approaching this arc. As a result, the final output gear 64 reliably and smoothly engages teeth 30g of  
25       cam gear 30 even when the loading drive gear set 61 moves



in a circular path vertically in conjunction with the movement of traverse base 20 in a circular path.

It should be noted that a loading drive mechanism for driving the disk loading mechanism comprises basically the loading drive gear set 61 and cam gear 30, or more specifically the teeth 30g thereof, and this loading drive mechanism corresponds to the loading drive mechanism of the accompanying claims.

The above-noted optical pickup 6 can move to a specified position on the inside circumference side of the data signal recording area of the disc 9. When the optical pickup 6 is then moved by the drive power of second motor 4 via the gear set 51 from the outside circumference side of the disc 9 to the inside circumference side, and reaches said specified position outside of the data signal recording area of the disc 9, the transfer path of second motor 4 drive power is switched to the loading drive gear set 61.

This transfer path switching operation is described further in detail with reference to Fig. 14 to Fig. 18. A vertical stud 20s is disposed at the front of the traverse base 20. A trigger lever 71 for switching the power transfer path is held on the stud 20s. A rocking lever 73 restricting the position of the trigger lever 71 is provided nearby.

As shown in detail in Fig. 35 to Fig. 37, the trigger lever 71 comprises a base 71b fit rotatably on the stud 20s, a partial gear 71g formed to part of the outside of the base 71b, and a pair of engaging arms 71a for  
 5 engaging the cam gear 30. A stop 71s for engaging claw 73d of rocking lever 73 is provided on the outside of the trigger lever base 71b.

The partial gear 71g is for engaging the power transfer path switching rack 42. The engaging arm 71a is  
 10 also disposed so that it can engage the hook 32 protruding from the outside of the cam gear 30.

As shown in detail in Fig. 38 to Fig. 40, the rocking lever 73 comprises a base 73b that is fit and fastened at the front of traverse base 20, a lever part 73a  
 15 extending in a basic L shape from the base 73b, and a spring part 73c extending basically in an arc from the base 73b. A claw 73d for engaging the stop 71s of trigger lever 71, and a pin 73p protruding upward, are integrally molded to the lever part 73a. A guide slot 73s through which the  
 20 regulating rod 75s of positioning rod 75 slides freely is also formed in the base 73b.

As will be known from Fig. 30 and Fig. 32, a cam channel 43 with a curved shape when seen in plan view is provided in the back of the feed rack 40. The front end of  
 25 the cam channel 43 is open to the front of the feed rack 40.

The pin 73p of rocking lever 73 is thus able to engage and slide freely through this cam channel 43.

A positioning mechanism for precisely maintaining engagement of the various components disposed to the drive base 10 and traverse base 20 is also provided on the drive base 10 and traverse base 20.

More specifically, a positioning member 75 (positioning rod) for positioning the traverse base 20 side to side to the drive base 10 is disposed to the front of the traverse base 20. As shown in detail in Fig. 41 to Fig. 43, this positioning rod 75 comprises an engaging base 75b for engaging and sliding freely front-back in the front-back guide channel 26 formed in the top of traverse base 20, extension 75c projecting forward from the engaging base 75b, and regulating rod 75s extending front-back (top-bottom as seen in Fig. 14 to Fig. 18) at a position offset to the right from the engaging base 75b and extension 75c.

As noted above, this regulating rod 75s is inserted through and slides freely front-back in the guide slot 73s [75s, sic] formed in the base 73b of rocking lever 73. As described more fully below, after assembly the front of the extension 75c contacts spring part 73c of rocking lever 73 and is pushed thereby to the back. The back of the extension 75c can also contact the front of the feed rack 40 so that as the feed rack 40 moves to the front, the

entire positioning rod 75 also moves to the front.

As shown in Fig. 14 to Fig. 18, a positioning channel 13 into which the regulating rod 75s of the positioning rod 75 can enter and fit is provided in the front end wall of the internal space 10H of drive base 10. When the feed rack 40 moves further than a specific distance to the front, the front of the feed rack 40 contacts and pushes on the back of the extension 75c of positioning rod 75, causing the entire positioning rod 75 to advance with the engaging base 75b following the guide channel 26. This causes the regulating rod 75s to fit into the positioning channel 13 of the drive base 10, and thus accurately positions the traverse base 20 side to side to the drive base 10.

A cam channel 27 shaped like an arc when seen in plan view is also provided in the top at the front of the traverse base 20. An engaging protrusion 32p is also provided on the back of the hook 32 on cam gear 30. This engaging protrusion 32p engages the cam channel 27, and thus regulates the front-back position of the traverse base 20 to the drive base 10.

The vertical positioning between the front of the traverse base 20 and the drive base 10 is also accurately controlled by the protrusion 20P provided at the front of traverse base 20 engaging the cam channel 33 of cam gear 30.

The position of the front of traverse base 20 to the drive base 10 is thus accurately determined in three perpendicular directions, that is, side to side, front to back, and vertically, and the components mounted on the drive base 10 and traverse base 20 can be accurately and reliably engaged with corresponding parts. It is therefore possible when switching the transfer path of second motor 4 drive power to accurately maintain linkage between the disk loading mechanism on the drive base 10 and the loading drive mechanism on the traverse base 20.

The disk drive 1 also has a clamping plate 95 with an assembled clamper 96 for clamping a disc 9 to the turntable 5 (see Figs. 1, 2, 4, 22, and 23). The clamper 96 has a magnet 97 in the center thereof, and felt 98 affixed to the disk contact surface on the bottom of the clamper 96.

A claw 95d is formed at each of the plurality of mounting arms 95f (two are provided at front and back in this exemplary embodiment) disposed to right and left sides of the clamping plate 95. The clamping plate 95 is assembled to the drive base 10 by engaging these claws 95d with the sides of the drive base 10. By thus assembling the clamping plate 95 to the drive base 10, the center of the clamper 96 can be centered with the center of turntable 5 rotation.

The clamping plate 95 comprises right and left

horizontal bases 95b for supporting mounting arms 95f on the same right and left sides, an annular center holder 95a for supporting the clamber 96, and a horizontal connector 95c for connecting the holder 95a to the bases 95b.

5 A notch 95e is formed on each side between the base of the holder 95a and the corresponding horizontal bases 95b. The width of each horizontal connector 95c is less than the width of the horizontal base 95b by an amount corresponding to the notch 95e. This gives the horizontal  
10 connectors 95c less rigidity than the horizontal bases 95b, and makes it easier for the horizontal connectors 95c to bend vertically.

When the disk drive 1 is dropped, for example, exposing the disk drive 1 to a large shock such that the  
15 turntable 5 contacts the clamping plate 95, the clamping plate 95 is able to easily flex in the vertical direction, thus absorb the force of impact, and therefore effectively prevent the turntable 5 (and spindle motor 3 linked to the turntable 5) from suffering major damage.

20 The operation of a disk drive 1 thus comprised is described next below.

When a disc 9 is loaded into the disk drive 1 and a signal recorded to the disc 9 is being reproduced by the optical pickup 6 (see Fig. 9), the traverse base 20 is  
25 supported substantially parallel to the drive base 10 as

shown in Fig. 6 by means of the protrusion 20P at the front edge of the traverse base 20 fit into the top horizontal channel 33a of the cam channel 33 in cam gear 30.

The stop 71s of the trigger lever 71 is engaged with the claw 73d of rocking lever 73, and the engaging arm 71a engages the hook 32 of cam gear 30, at this time as shown in Fig. 14. When thus engaged, the trigger lever 71 is turned all the way clockwise in Fig. 9 and Fig. 14.

To read a signal from the disc 9 in this position, the spindle motor 3 is driven to spin the turntable 5 on which the disc 9 is loaded at a specific speed, the optical pickup 6 is moved to a position below the signal track to be reproduced, and the optical elements (that is, the optical system including a laser and lens) of the optical pickup 6 are operated to read the desired signal from the disc 9.

If the signal track to be reproduced is not above the current optical pickup 6 position, or if signals are to be read from some plurality of signal tracks, the optical pickup 6 must be moved appropriately toward the inside circumference of the disc 9, that is, toward the front of the disk drive 1, or the outside circumference of the disc 9, that is, toward the back of the disk drive 1.

The optical pickup 6 is moved by means of the optical pickup drive mechanism. As described above, the

second motor 4 is therefore driven and the motor gear 4G turns. Rotation of the motor gear 4G is speed reduced at a specific speed reducing ratio and transferred to the output side by the rack drive gear set 51, thereby causing the final output gear 53B (second traverse output gear) to turn at a reduced speed and moving the feed rack 40 and the optical pickup 6 linked thereto front or back. If the motor gear 4G turns counterclockwise in Fig. 9 to Fig. 13, the optical pickup 6 moves forward (downward in Fig. 9 to Fig. 13) toward the inside circumference of the disc 9. If the motor gear 4G turns in the opposite direction, the optical pickup 6 moves to the back (upward in Fig. 9 to Fig. 13) toward the outside circumference of the disc 9.

It should be noted that the loading drive gear set 61 also turns in conjunction with second motor 4 operation during this signal reproduction mode, but the teeth of the third loading gear 64, that is, the final output gear of the gear set 61, are positioned at the smooth part 34 of the cam gear 30 and thus do not engage the cam gear teeth 30g. Drive power from the second motor 4 is therefore not transferred to the cam gear 30, and hence to the tray drive gear 56, in this signal reproduction mode.

Fig. 10 and Fig. 15 show the drive train when positioned for reading a signal recorded to the most inside circumference part of the recording position range (data



signal recording area) of the disc 9. When positioned to read from this disc area, the optical pickup 6 is moved forward by the optical pickup drive mechanism to the inside circumference edge  $S_r$  of the data signal recording area of the disc 9, and the back end of the driven rack part 41 of the feed rack 40 is engaged with the final output gear 53B (second traverse output gear) of the rack drive gear set 51. The power transfer path switching rack 42 is also extremely close to the partial gear 71g of trigger lever 71.

10       The data signal recording area of an optical disc 9 is known from the literature to be determined by the distance from the disc center based on the disk format standard. A conventional disk drive also has an optical pickup position detector disposed at a position  
15       corresponding to the most inside circumference position of the data signal recording area to detect whether the optical pickup is at this most inside circumference position or has moved thereto so that the optical pickup can be prevented from moving beyond this point further  
20       towards the inside circumference of the disc.

      In contrast to this conventional design, a disk drive 1 according to this preferred embodiment has an inside circumference detection switch 7 disposed at the inside circumference edge  $S_r$  of the data signal recording  
25       area of the disc 9, and uses the inside circumference edge

Sr as an inside circumference edge switching position. When off, this inside circumference detection switch 7 operates the same as in a conventional optical disk drive to detect whether the optical pickup is at this most inside circumference position or has moved thereto. What differs from the conventional disk drive is that when the inside circumference detection switch 7 is on, movement of the optical pickup 6 beyond the inside circumference edge Sr is not limited when the optical pickup 6 trips the inside circumference detection switch 7, and the optical pickup 6 can therefore be purposely moved further to the inside circumference of the disc 9.

The inside circumference detection switch 7 operates mechanically in the same manner as a common conventional detector, and is disposed to project and retract vertically to the top of the traverse base 20. When the optical pickup 6 reaches a position above the inside circumference detection switch 7, the bottom of the optical pickup 6 interferes with the switch 7, causing the inside circumference detection switch 7 to be pushed into the traverse base 20 in resistance to the pressure of a switch spring (not shown in the figure). It should be noted that this inside circumference detection switch 7 shall not be limited to a mechanical device such as described above, and can alternatively be a non-contact detector or any of

various other known designs.

Fig. 11 and Fig. 16 show the optical pickup 6 after it has moved to the inside circumference edge  $S_r$ , operated the inside circumference detection switch 7, and then moved beyond this position farther to the inside circumference of the disc 9.

The differences between the state shown in Figs. 10 and 15 and the state shown in Figs. 11 and 16, as well as the movement to these states, are described next below.

The optical pickup 6 is moved from the state shown in Figs. 10 and 15 to the state shown in Figs. 11 and 16 by continuing to drive the second motor 4 in the same direction (counterclockwise in this case) from the state shown in Figs. 10 and 15 after the optical pickup 6 operates the on-state inside circumference detection switch 7.

By thus moving the optical pickup 6 further to the inside circumference, the power transfer path switching rack 42 of the feed rack 40 moving the optical pickup 6 front-back engages the partial gear 71g of trigger lever 71, and turns the trigger lever 71 clockwise. In conjunction with this the engaging arm 71a of trigger lever 71 turns the hook 32 of cam gear 30 counterclockwise.

The cam gear 30 thus turns counterclockwise, and the cam gear teeth 30g begin to engage the final output

gear 64 (third loading gear) of the loading drive gear set 61. The driven rack part 41 of the feed rack 40 is still engaged with the final output gear 53B (second traverse output gear) of the rack drive gear set 51 at this time.

5 The rocking lever 73 engaged with the stop 71s of the trigger lever 71 to position and hold the trigger lever 71 also turns as a result of the rocking lever pin 73p following the cam channel 43 of feed rack 40. As a result, the claw 73d releases the trigger lever 71.

10 Fig. 12 and Fig. 17 show the state in which the cam gear 30 is turned counterclockwise by drive power from the third loading gear 64 from where the cam gear 30 begins to engage the final output gear 64 (third loading gear) of the loading drive gear set 61.

15 This operation is also accomplished by the motor gear 4G of second motor 4 turning counterclockwise, that is, in the same direction in which the motor gear 4G turns to move the optical pickup 6 to the inside circumference.

20 This operation of the cam gear 30 turns the trigger lever 71 clockwise to a position limited by the cam gear 30, thus drawing the optical pickup 6 to a further inside circumference position (forward position) until the driven rack part 41 of the feed rack 40 disengages the second traverse output gear 53B. As a result, further  
25 counterclockwise rotation of the motor gear 4G, and hence

drive power from the second motor 4, is not transferred to the feed rack 40, that is, to optical pickup 6 movement.

The pin 73p of rocking lever 73 is guided along the cam channel 43 of feed rack 40 to enter the inclined part of the cam channel 43 at this time, and is thus turned counterclockwise by the spring tension of the rocking lever 73. The trigger lever 71 continues to be turned clockwise until it completely separates from the cam gear 30.

It should be noted that basically the trigger lever 71, rocking lever 73, and cam gear 30 (or more specifically the hook 32 and smooth part 34 of the cam gear 30), as well as more specifically the power transfer path switching rack 42 and cam channel 43 of the feed rack 40, combine to form a power transfer path switching mechanism for switching the transfer path of second motor 4 drive power. This power transfer path switching mechanism corresponds to the power transfer path switching mechanism of the accompanying claims.

As described above, the feed rack 40 can move the optical pickup 6 to an inside circumference edge Sr position at the inside circumference limit of the data signal recording area of the disc 9, and can then continue moving the optical pickup 6 beyond this position closer to the inside circumference of the disc 9. Furthermore, the second motor 4 drive power transfer path is switched by the

feed rack 40 moving to this specific position at the inside circumference or moving from this specific position toward the outside circumference of the disc. As a result, drive power from a single motor (the second motor 4) can be used to power the signal reading operation of the optical pickup 6, as well as switching the drive power transfer path of the second motor 4.

Furthermore, by continuing to drive the same motor 4 without changing the direction of shaft rotation after moving the optical pickup 6 for signal reproduction to the inside circumference edge  $S_r$  of the data signal recording area of the disc 9, the disc 9 is automatically unclamped from the turntable 5 so that the disc 9 can be ejected from the disk drive. It is therefore possible to eliminate the dedicated disk loading motor required for disk loading and unloading in a conventional optical disk drive. It is therefore possible to provide a less expensive disk drive by thus reducing the number of motors used in the disk drive.

Furthermore, by changing the direction of second motor 4 operation or simply stopping the second motor 4 after the optical pickup 6 has been moved to the inside circumference edge  $S_r$  of the data signal recording area of the disc 9 and the position of the optical pickup 6 has been detected by the inside circumference detection switch

7, it is possible to not eject the disc 9 from the disk drive and continue reading or writing signals to the same disc 9.

The number of detectors or detection switches used in the disk drive can also be reduced, and a lower cost optical disk drive can therefore be provided, because the inside circumference detection switch 7 can be used to detect if a disk has been loaded into the disk drive and if the disk has been clamped, and dedicated detectors used in a conventional disk drive for these detection purposes can therefore be eliminated.

The traverse base 20 in a disk drive according to this preferred embodiment is designed to swing up and down on the back end of the base while a protrusion 20P at the front end engages a cam channel 33 in the cam gear 30. As described above, this cam channel 33 comprises top and bottom horizontal channels 33a and 33c and a diagonal channel 33b connecting these horizontal channels (see Fig. 24 to Fig. 29). The vertical position of the front of the traverse base 20 is determined by what part of these three channels 33a to 33c the protrusion 20P is engaged with, that is, by the direction and distance of cam gear 30 rotation. The traverse base 20 therefore swings up and down pivoting around the back edge of the traverse base 20 according to the direction and distance of cam gear 30

rotation.

It will thus be obvious that the traverse base 20 is supported to swing vertically on one edge thereof relative to the drive base 10. More specifically, the cam gear 30 is turned by power transferred from the loading drive gear set 61, causing the other end of the traverse base 20 to move up or down such that the front of traverse base 20 swings up or down relative to the drive base 10. Drive power from one motor, the second motor 4, is thus used to swing the traverse base 20 up and down, and therefore to raise or lower the turntable 5, and spin the disc 9 in conjunction therewith.

When the cam gear 30 moves further counterclockwise as shown in Fig. 13 and Fig. 18, the position at which the protrusion 20P of traverse base 20 engages the cam channel 33 moves from the top horizontal channel 33a through the diagonal channel 33b to the bottom horizontal channel 33c.

When the traverse base 20 is positioned as shown in Fig. 9 and Fig. 14, the protrusion 20P engages top horizontal channel 33a, and the traverse base 20 is held as shown in Fig. 6 parallel to the drive base 10 with the top of the traverse base 20 substantially flush with the top of the drive base 10. The disc 9 can thus be clamped and held level between the turntable 5 and the clamper 96.



When the feed rack 40 moves more than a specific distance forward as shown in Figs. 10 to 13 and Figs. 15 to 18, the cam gear 30 begins to turn, and the front protrusion 20P of the traverse base 20 passes the diagonal channel 33b to engage the bottom horizontal channel 33c of cam channel 33.

This results in the traverse base 20 swinging down on the back end thereof so that it is inclined to the drive base 10 as shown in Fig. 7. This movement of the traverse base 20 also lowers the turntable 5 to the same downward incline. As a result, a disc 9 can be drawn to a position above the turntable 5 from outside the disk drive 1, or can be ejected from above the turntable 5 to outside the disk drive 1, without the disc 9 or turntable 5 interfering with disc 9 loading or unloading.

When the traverse base 20 is thus inclined down from the drive base 10 to a specific position (the position at which the front protrusion 20P of the traverse base 20 passes the diagonal channel 33b and engages the bottom horizontal channel 33c of cam channel 33), the teeth 30g of cam gear 30 engage the tray drive gear 56 of the disk loading mechanism. The tray 55 is thus driven with the traverse base 20 reliably swung to a downward position.

It is therefore possible to reliably avoid interference between the tray 55 (and disc 9 thereon) and

the turntable 5 when the tray is driven (that is, when a disk is loaded or unloaded).

When the traverse base 20 is thus inclined (see Fig. 13, Fig. 18, and Fig. 7), the third loading gear 64 is also inclined and engaged with the teeth 30g of cam gear 30. As noted above and shown in Fig. 29, these teeth 30g have a profile in longitudinal section that is curved or inclined to the axis Lg of the cam gear 30. As a result, gears 64 and 30g can engage reliably and smoothly.

Furthermore, while the feed rack 40 (that is, the optical pickup 6) moves to the front and the traverse base 20 is inclining, the front edge of the feed rack 40 contacts and pushes forward on the back of the extension 75c of positioning rod 75 in conjunction with the forward movement of the feed rack 40 as shown in Figs. 14 to 18. This causes the regulating rod 75s of the positioning rod 75 to move forward guided by the guide slot 73s in the base 73b of rocking lever 73. Then, as noted above, the regulating rod 75s fits into the positioning channel 13 in drive base 10, and thus positions the traverse base 20 side to side to the drive base 10.

When the feed rack 40 moves in the opposite direction to the back, the force of spring part 73c moves the positioning rod 75 to the back. This is because the front of the extension 75c of positioning rod 75 contacts

the spring part 73c of the rocking lever 73, and the spring part 73c thus constantly urges the positioning rod 75 toward the back.

When the traverse base 20 is held substantially parallel to the drive base 10 with the tops thereof substantially flush, the drive base 10 and traverse base 20 are positioned front-back to each other by engagement of the engaging protrusion 32p of hook 32 on cam gear 30 with the cam channel 27 in the front of traverse base 20.

Fig. 19 and Fig. 20 show the state in which the motor gear 4G is driven further in the same direction (counterclockwise) by the second motor 4, and cam gear 30 is turned further counterclockwise by way of intervening loading drive gear set 61. The input gear 56A of tray drive gear 56 does not engage the teeth 30g of traverse base 20, and is positioned to the smooth part 34, in the states shown in Figs. 9 to 13. Rotation of cam gear 30 is therefore not transferred to the tray drive gear 56, and the tray drive gear 56 does not turn.

However, when the cam gear 30 turns to the position shown in Fig. 19 and Fig. 20, teeth 30g of cam gear 30 begin to engage input gear 56A of tray drive gear 56, and tray drive gear 56 turns in conjunction with rotation of the cam gear 30. The tray 55 is then pulled to the front as shown in Fig. 21 by way of output gear 56B of

tray drive gear 56 and the tray rack teeth 55g engaged therewith.

It should be noted that drawing the tray 55 from inside the disk drive 1 to outside the drive, that is, unclamping the disc 9 and ejecting the disc 9 from a signal reproduction state, is described above. To draw the tray 55 from outside to inside the disk drive 1, the second motor 4 is driven in the opposite direction by the motor control circuit of the circuit board 2 so that the motor gear 4G begins to turn clockwise. As a result, carrying the optical disc 9 into the disk drive 1, clamping the disc, and preparing for signal reproduction are accomplished as a sequence of actions.

As described above, a disk drive according to this particular embodiment of the present invention comprises a drive base 10 and separate traverse base 20 to which a turntable 5 is assembled with the traverse base 20 supported so as to swing up and down on the drive base 10. By driving a single motor (second motor 4) continuously in a forward direction (first direction of rotation) or opposite direction, moving an optical pickup 6, raising and lowering the turntable 5, and transporting a disc 9 can be accomplished substantially continuously in this order, or substantially continuously in the opposite order. It is therefore possible when loading or unloading a disc 9 to

avoid interference with the turntable 5 without moving the disc 9 up or down. Unlike with a conventional disk drive, it is therefore not necessary to provide a disk holder for lifting the disk.

5           Furthermore, it is also possible to secure (clamp) and release (unclamp) the disc 9 to or from the turntable 5 using the operation whereby the traverse base 20 to which the turntable 5 is assembled is swung vertically on the drive base 10. Therefore, unlike with a  
10 conventional disk drive, it is not necessary to drive the clamping mechanism (chucking plate) up and down.

          Furthermore, because a single motor (second motor 4) is used to move the optical pickup 6, raise and lower the turntable 5, and transport the disc 9, the disk drive 1  
15 can be operated using a total of two motors, that is, said second motor 4 and a spindle motor (first motor) 3 for rotationally driving the turntable 5. By thus reducing the number of motors used, disk drive 1 construction is simplified, and good operation of the component parts can  
20 be more stably maintained.

#### Advantages of the present invention

          In an optical disk drive according to a first aspect of the present invention, both a first base  
25 comprising a base frame of the disk drive, and a second

base separate from the first base are provided. The second base is supported to move or swing vertically relative to the first base. A single motor (the above-noted second motor) can be driven continuously forward (in a first direction of rotation) or in the opposite direction to move the optical pickup, raise or lower the turntable, and move the optical disc substantially continuously in this sequence, or substantially continuously in reverse direction in reverse sequence. It is therefore possible to avoid interference between the turntable and disk when loading and unloading a disk without moving the disk up or down. Unlike with a conventional disk drive, it is therefore not necessary to provide a disk holder for lifting the disk.

Furthermore, it is also possible to secure (clamp) and release (unclamp) the disc to or from the turntable using the operation whereby the second base to which the turntable is assembled is swung vertically on the first base. Therefore, unlike with a conventional disk drive, it is not necessary to drive the clamping mechanism (chucking plate) up and down.

Furthermore, because a single motor (the second motor) is used to move the optical pickup, raise and lower the turntable, and transport the disc, the disk drive can be operated using a total of two motors, that is, said

second motor and a first motor for rotationally driving the turntable. By thus reducing the number of motors used, disk drive construction is simplified, and good operation of the component parts can be more stably maintained.

5        In an optical disk drive according to a second aspect of the present invention, the second base is disposed inside an opening in the first base, and is supported so that it can swing vertically pivoting around one end thereof relative to the first base. More  
10 specifically, the cam gear is rotated by drive power transferred from the loading drive gear set, and the other end side of the second base is raised or lowered in conjunction with cam gear rotation. As a result, the second base is moved up or down to the first base pivoting around  
15 the one end side of the second base.

      In addition to the benefits achieved by the first aspect of the invention, it is also possible to use drive power from a single motor (the second motor) to drive and link pivoting the second base up and down to the first base  
20 (that is, raising and lowering the turntable), and transport (load and unload) the disk.

      In an optical disk drive according to a third aspect of the present invention, the profile of the outside gear part of the cam gear as seen in longitudinal section  
25 is an arc or a line approaching said arc. This arc follows

a path of vertical circular motion through which the final output gear of the loading drive gear set travels in conjunction with the swinging movement of the second base.

In this case the final output gear of the loading drive gear set positively engages the outside gear part of the cam gear when the final output gear swings up or down in conjunction with the swinging movement of the second base.

In an optical disk drive according to a fourth aspect of the present invention, a protrusion is disposed to said other end side of the second base, and this other end side of the second base is positioned vertically as a result of this protrusion engaging a cam channel in the cam gear.

Therefore, in addition to the benefits achieved by the above aspects of the invention, it is also possible to reliably determine and precisely position the other end side of the second base vertically to the first base. As a result, components on the first base and components on the second base can be precisely and reliably engaged with corresponding components.

In an optical disk drive according to a fifth aspect of the present invention, the outside gear part of the cam gear engages the tray drive gear of the disk loading mechanism when the second base swings downward to a



specific position relative to the first base. The tray is thus driven after the second base has positively swung down from the first base.

Therefore, in addition to the benefits achieved  
5 by the above aspects of the invention, it is also possible to reliably avoid interference between the tray (that is, the disk on tray) and the turntable when the tray is driven (that is, when the disk is transported).

In an optical disk drive according to a sixth  
10 aspect of the present invention, the feed rack can be moved to a specific position farther to the inside circumference side of the disc after moving the optical pickup to an inside circumference edge position of the data signal recording area of the optical disc. By moving to this  
15 specific position at the inside circumference side, or moving from said specific position at the inside circumference side to the outside circumference side of the disc, the feed rack switches the drive power transfer path of the second motor.

20 Therefore, in addition to the benefits achieved by the above aspects of the invention, it is also possible to use a single motor (the second motor) to drive signal reading operations of the optical pickup, and switching the drive power transfer path of the second motor.

25 In an optical disk drive according to a seventh

aspect of the present invention, a regulating rod is driven to project from the other end side of the second base as result of the feed rack moving beyond a specific position to the other end side. The regulating rod thus fits into the positioning channel in the first base, and thereby  
5 determines the lateral position of the second base to the first base perpendicular to the direction of feed rack travel.

Therefore, in addition to the benefits achieved  
10 by the above aspects of the invention, it is also possible to precisely and positively position the other end side of the second base laterally to the first base. In addition, components on the first base and components on the second base can be precisely and reliably engaged with  
15 corresponding components. Furthermore, moving the feed rack to the other end side of the second base and positioning the second base can be interlinked using drive power from a single motor (the second motor).

In an optical disk drive according to an eighth  
20 aspect of the present invention, the second base can additionally be positively positioned to the first base in the direction of feed rack travel as a result of a hook part disposed to the cam gear engaging a curved channel in the second base. As a result, components on the first base  
25 and components on the second base can be precisely and

reliably engaged with corresponding components.

In addition to the benefits achieved by the above aspects of the invention, the second base is not rigidly supported on the first base as in a conventional disk drive, but is instead supported so as to float on the first base within limits determined by the flexibility of the damping members, in an optical disk drive according to a ninth aspect of the present invention.

As a result, strong shocks or vibrations to which the optical disk drive is exposed can be absorbed by the damping members, and thus prevented from being transferred directly from the first base to drive parts on the second base. This means that the durability of the disk drive can be improved with respect to shock and vibration.

Furthermore, by supporting the second base so that it can float on the first base within the range of damping member flexibility, it is possible to adjust the relative positions of components on the first base and second base within the floating range of the second base. Compared with a conventional disk drive in which the components are rigidly supported, it is therefore possible to require less precision in parts manufacture and assembly, and productivity can therefore be improved in the manufacturing process.

Although the present invention has been described

in connection with particular embodiments thereof with reference to the accompanying drawings, it is to be noted that various changes and modifications will be apparent to those skilled in the art. Such changes and modifications are to be understood as included within the scope of the present invention as defined by the appended claims, unless they depart therefrom.

CLAIMS

1. An optical disk drive having a turntable for rotatably supporting an optical disc, an optical pickup for writing a data signal to an optical disc rotating on the turntable and/or reading a data signal recorded to said optical disc, a pickup drive mechanism for moving the optical pickup bidirectionally between the inside circumference side and outside circumference side of the optical disc, and a disk loading mechanism for moving an optical disc bidirectionally between a first position at which the optical disc is above the turntable, and a second position at which the optical disc is outside the disk drive, comprising:

a first base having a base frame of the disk drive and a second base separate from the first base and supported to move or swing vertically relative to the first base, the second base having disposed thereto said turntable and a first motor for rotationally driving said turntable, and said optical pickup and pickup drive mechanism;

wherein a loading drive mechanism for driving said disk loading mechanism, a second motor drivable in forward and reverse directions for supplying drive power to said loading drive mechanism and pickup drive mechanism, and a drive power transfer path switching mechanism for switching the drive power transfer path of the second motor between a path transferring power to the loading drive mechanism and a path transferring power to the pickup drive mechanism, are disposed on the first and/or second base; and

moving said optical pickup, raising or lowering the turntable, and moving the optical disc can be substantially continuously performed in sequence by driving said second motor continuously in a first direction of rotation,

5       and these operations can be performed in reverse direction in reverse sequence substantially continuously by driving said second motor continuously in the reverse of said first direction of rotation.

2.       An optical disk drive as described in claim 1, wherein said second base is disposed inside an opening in the first base, and vertically swingably supported around one end thereof relative to the first base;

the first base comprises thereon a cam gear disposed near an other end side of the second base, said cam gear having on an outside surface thereof a cam channel for raising and lowering said other end of said second

base; and

said loading drive mechanism comprises a loading drive gear set containing a plurality of gears including a final output gear;

5        said final output gear of the loading drive gear set engaging an outside teeth part of the cam gear to rotate said cam gear and thereby raise or lower said other side of the second base.

10    3.        An optical disk drive as described in claim 2, wherein the profile of the outside gear part of the cam gear as seen in longitudinal section is an arc or a line approaching said arc,

15        said arc following a path of vertical circular motion through which said final output gear of the loading drive gear set travels in conjunction with the swinging movement of the second base.

20    4.        An optical disk drive as described in claim 2 or claim 3, wherein a protrusion is disposed to said other end side of the second base, and

said other end side of the second base is positioned vertically by said protrusion engaging a cam channel in the cam gear.

25

5. An optical disk drive as described in any of claims 2 to 4, wherein said disk loading mechanism comprises a tray drive gear for driving the tray on which a disk is placed,

said outside gear part of the cam gear engaging said tray drive gear when the second base swings downward to a specific position relative to the first base.

6. An optical disk drive as described in any of claims 2 to 5, wherein the pickup drive mechanism comprises a feed rack for moving an optical pickup, and a rack drive gear set comprising a plurality of gears for driving said feed rack,

15        said feed rack being movable to a specific position farther to the inside circumference side after moving the optical pickup to an inside circumference edge position of the data signal recording area of the optical disc,

engaging said drive power transfer path  
switching mechanism by moving to this specific position at  
the inside circumference side and thereby switching second  
motor drive power transfer path from a path to the pickup  
drive mechanism to a path to the loading drive mechanism,  
and

switching said second motor drive power



transfer path from a path to the loading drive mechanism to a path to the pickup drive mechanism by moving from said specific position at the inside circumference side to the outside circumference side of the disc and thereby  
5 disengaging from the drive power transfer path switching mechanism.

7. An optical disk drive as described in claim 6, wherein a regulating rod retractable from the other end  
10 side is disposed to the second base, and

a positioning channel engageable by said regulating rod is disposed in said first base;

said feed rack engaging said regulating rod when it moves from the one end side to the other end side of the  
15 second base and reaches a specific position, and

said regulating rod protrudes from the other end side of the second base and fits into said positioning channel when the feed rack moves further toward the other end side after engaging the regulating rod, thereby  
20 positioning the second base to the first base in a lateral direction perpendicular to the direction of feed rack travel.

8. An optical disk drive as described in claim 6 or  
25 claim 7, wherein the cam gear comprises a hook part

projecting to the outside,

the second base comprises on a surface thereof a curved channel parallel to an outside part of the cam gear,

5 and

said hook part engages said curved channel to position the second base to the first base in the direction of feed rack travel.

10 9. An optical disk drive as described in any of claims 2 to 8, wherein an elastic damping member is disposed to a support part for supporting said one end side of the second base to the first base, and to a support part for supporting said cam gear to the first base,

15 said second base being thus supported in a floating state on the first base within the range of elasticity of said damping members.

20 10. An optical disk drive substantially as herein described with reference to and as illustrated by the accompanying drawings.



INVESTOR IN PEOPLE

Application No: GB 0002315.0  
Claims searched: All

Examiner: Rebecca Willis  
Date of search: 16 June 2000

## Patents Act 1977 Search Report under Section 17

### Databases searched:

UK Patent Office collections, including GB, EP, WO & US patent specifications, in:

UK CI (Ed.R): G5R (RPC6), (RPX)

Int CI (Ed.7): G11B 17/028, 17/03

Other: Online: EPODOC, WPI, PAJ

### Documents considered to be relevant:

Category	Identity of document and relevant passage	Relevant to claims
X	GB 2121989 A (TANAKA) (see page 2 lines 17-24 and figs. 2 and 3, and see page 3 line 63 - page 4 line 5 and fig. 11)	1
X	EP 0174629 A2 (KOMOSHITA) (see page 3 line 15 - page 4 line 2 and page 19 lines 5-9)	1

X	Document indicating lack of novelty or inventive step	A	Document indicating technological background and/or state of the art.
Y	Document indicating lack of inventive step if combined with one or more other documents of same category.	P	Document published on or after the declared priority date but before the filing date of this invention.
&	Member of the same patent family	E	Patent document published on or after, but with priority date earlier than, the filing date of this application.